



ISWI & MAGDAS SCHOOL

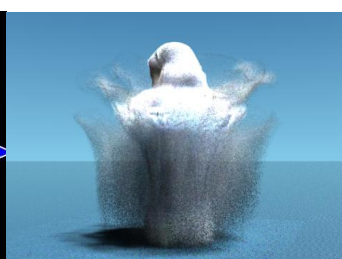
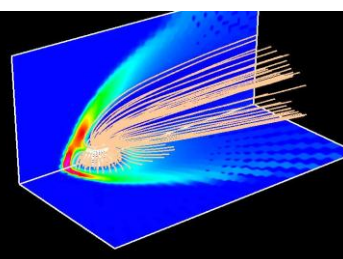
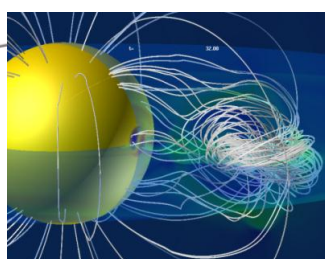
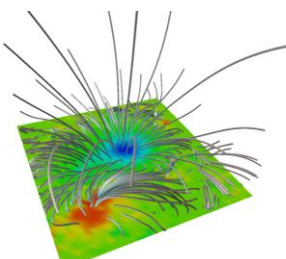
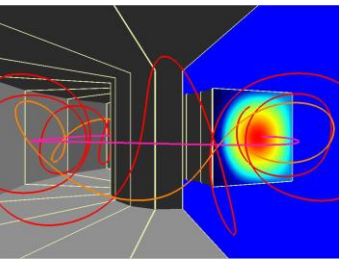
Wisma Pandawa, West Java, Indonesia

17-23 September 2012

Solar Magnetohydrodynamics

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Nagoya University



Dynamic Sun





Outlook

- Introduction to Magnetohydrodynamics
 - Alfvén's theorem (frozen-in)
- Magnetic Structure in Solar Active Region
 - Solar magnetic field
 - MHD equilibrium
 - Magnetic helicity and free energy
 - Force-free field model

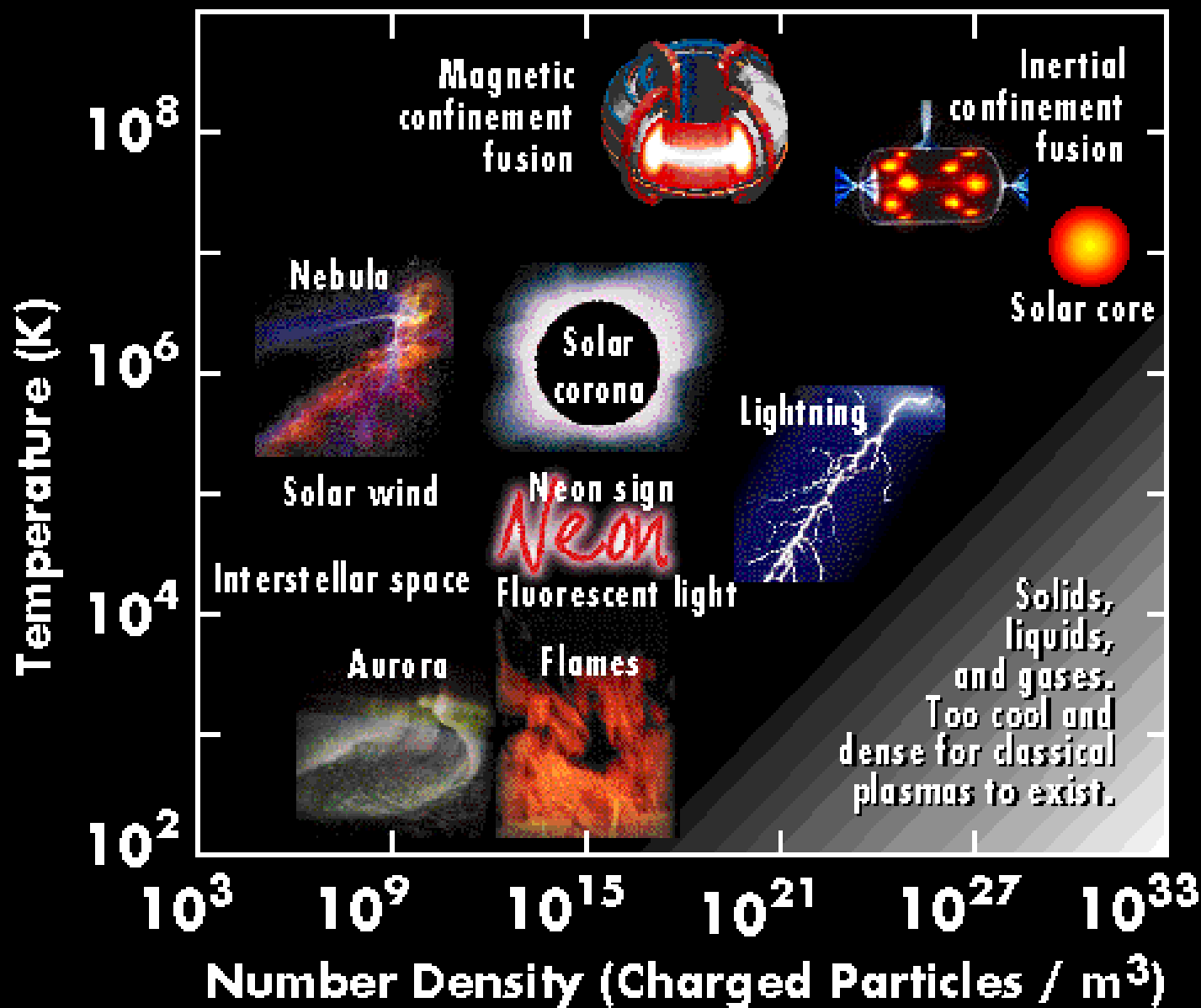
- Dynamics in solar coronal magnetic field
 - Solar eruptions (flare and CME)
 - Magnetic reconnection
- What triggers the onset of solar eruptions? [NEW]
 - Ensemble 3D MHD simulation study
 - Hinode Observations
 - Discussion: Predictability of solar eruptions

Introduction to MHD



Hannes Alfvén

Plasmas



Plasma Dynamics

mechanics

g: gravitational field

P: pressure

m, V
Plasma motion
(electron, ions)

macroscopic view point
&
microscopic view point
Equations of motion

electromagnetism

B: Magnetic field

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$

E: Electric field

$$\nabla \cdot \mathbf{B} = 0$$

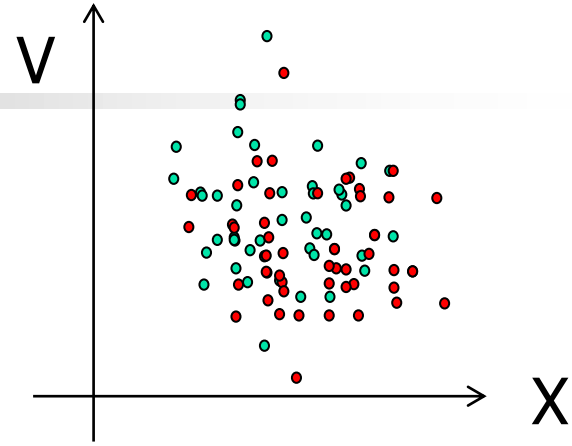
$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

Maxwell equations

Klimontvich equation

$$\frac{\partial \hat{F}_s}{\partial t} + \mathbf{v} \cdot \frac{\partial \hat{F}_s}{\partial \mathbf{r}} + \hat{K}_s \cdot \frac{\partial \hat{F}_s}{\partial \mathbf{v}} = 0$$



$$\hat{F}_s(\mathbf{r}, \mathbf{v}, t) = \sum_{j=1}^{N_s} \delta[\mathbf{r} - \mathbf{r}_j(t)] \delta[\mathbf{v} - \mathbf{v}_j(t)], \quad \hat{K}_s(\mathbf{r}, \mathbf{v}, t) = \frac{q_s}{m_s} [\hat{\mathbf{E}}(\mathbf{r}, t) + \mathbf{v} \times \hat{\mathbf{B}}(\mathbf{r}, t)]$$

where $\delta[\mathbf{a}] = \delta(a_x) \delta(a_y) \delta(a_z)$

$$\hat{\mathbf{J}}_s(\mathbf{r}, t) = \sum_s q_s \int \mathbf{v} \hat{F}_s(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$$

$$\hat{\sigma}_s(\mathbf{r}, t) = \sum_s q_s \int \hat{F}_s(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$$

$$\nabla \times \hat{\mathbf{E}}(\mathbf{r}, t) = - \frac{\partial \hat{\mathbf{B}}(\mathbf{r}, t)}{\partial t}$$

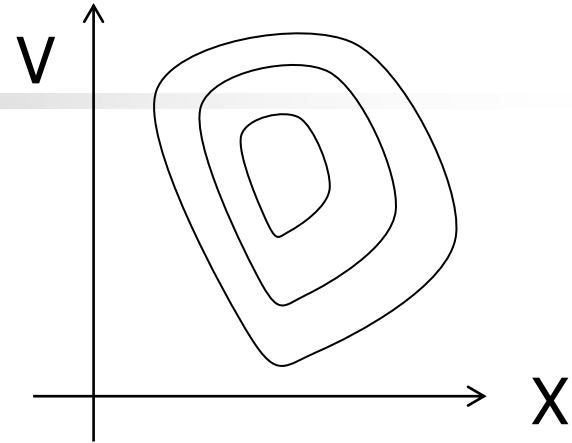
$$\nabla \times \hat{\mathbf{B}}(\mathbf{r}, t) = \frac{1}{c^2} \frac{\partial \hat{\mathbf{E}}(\mathbf{r}, t)}{\partial t} + \mu_0 \hat{\mathbf{J}}(\mathbf{r}, t)$$

$$\nabla \cdot \hat{\mathbf{B}}(\mathbf{r}, t) = 0$$

$$\nabla \cdot \hat{\mathbf{E}}(\mathbf{r}, t) = \frac{1}{\epsilon_0} \hat{\sigma}_e(\mathbf{r}, t)$$

Vlasov equation

$$\frac{\partial F_s}{\partial t} + \mathbf{v} \cdot \frac{\partial F_s}{\partial \mathbf{r}} + K_s \cdot \frac{\partial F_s}{\partial \mathbf{v}} = 0$$



$$F_s(\mathbf{r}, \mathbf{v}, t) = \langle \hat{F}_s(\mathbf{r}, \mathbf{v}, t) \rangle = \int d\{\mathbf{r}_i, \mathbf{v}_i\} D(\{\mathbf{r}_i, \mathbf{v}_i\}; t) F_s(\mathbf{r}, \mathbf{v}, \{\mathbf{r}_i, \mathbf{v}_i\})$$

ensemble average

$$\mathbf{J}_s(\mathbf{r}, t) = \sum_s q_s \int \mathbf{v} F_s(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$$

$$\sigma_s(\mathbf{r}, t) = \sum_s q_s \int F_s(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$$

$$\nabla \times \mathbf{E}(\mathbf{r}, t) = -\frac{\partial \mathbf{B}(\mathbf{r}, t)}{\partial t}$$

$$\nabla \times \mathbf{B}(\mathbf{r}, t) = \frac{1}{c^2} \frac{\partial \mathbf{E}(\mathbf{r}, t)}{\partial t} + \mu_0 \mathbf{J}(\mathbf{r}, t)$$

$$\nabla \cdot \mathbf{B}(\mathbf{r}, t) = 0$$

$$\nabla \cdot \mathbf{E}(\mathbf{r}, t) = \frac{1}{\epsilon_0} \sigma_e(\mathbf{r}, t)$$

Macroscopic Variables

- the n-th moment in velocity space

$$\mathbf{M}^n = \int \mathbf{v}^n F_s(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$$

$$n_s(\mathbf{r}, t) = \mathbf{M}^0 = \int F_s(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$$

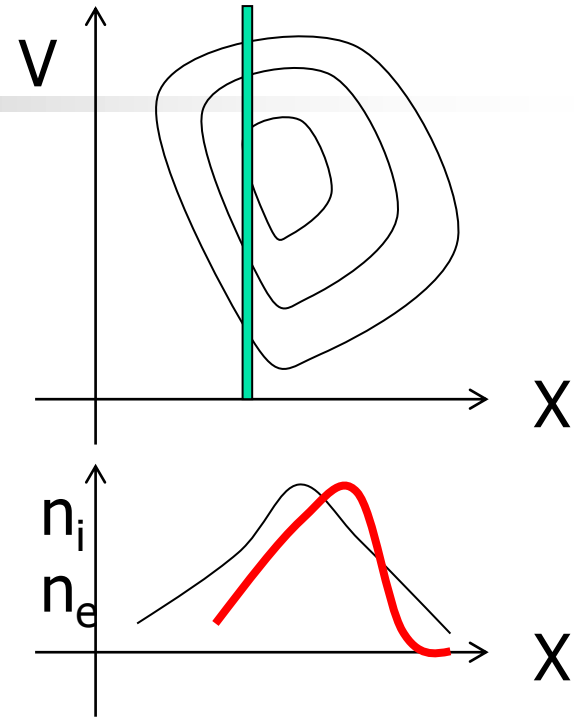
$$\Gamma_s(\mathbf{r}, t) = \mathbf{M}^1 = \int \mathbf{v} F_s(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$$

$$\mathbf{u}_s(\mathbf{r}, t) = \bar{\mathbf{v}}_s(\mathbf{r}, t) = \Gamma_s(\mathbf{r}, t) / n_s(\mathbf{r}, t)$$

$\mathbf{c} = \mathbf{v}_s - \mathbf{u}_s$ *velocity fluctuation* (速度揺らぎ)

$$\tilde{\mathbf{P}}_s(\mathbf{r}, t) = m_s \mathbf{M}^2 = m_s \int \mathbf{c} \mathbf{c} F_s d\mathbf{v}$$

$$Q_s(\mathbf{r}, t) = \frac{1}{2} m_s \int \mathbf{c} \mathbf{c}^2 F_s d\mathbf{v}$$



Macroscopic Equations

$$\int \mathbf{v}^n \left[\frac{\partial F_s}{\partial t} + \mathbf{v} \cdot \frac{\partial F_s}{\partial \mathbf{r}} + K_s \cdot \frac{\partial F_s}{\partial \mathbf{v}} = \left(\frac{\delta F}{\delta t} \right)_{\text{collision}} \right] d\mathbf{v}$$

moment in velocity space

$$n = 1 \quad \frac{\partial n_s}{\partial t} + \nabla \cdot (n_s \mathbf{u}) = 0$$

$$n = 2 \quad \frac{\partial}{\partial t} (\rho_s \mathbf{u}_s) + \nabla \cdot (\rho_s \mathbf{u}_s \mathbf{u}_s) + \nabla \cdot \tilde{\mathbf{P}}_s - \rho_{cs} \mathbf{a}_s = \left(\frac{\delta M_s}{\delta t} \right)_{\text{collision}}$$

$$n = 3 \quad \frac{\partial}{\partial t} \left(\frac{3}{2} \tilde{\mathbf{P}}_s + \frac{1}{2} \rho_s u_s^2 \right) + \nabla \cdot \left\{ \left(\frac{1}{2} \rho u_s^2 + \frac{5}{2} \tilde{\mathbf{P}}_s \right) \mathbf{u}_s + Q_s \right\} - \rho \mathbf{J} \cdot \mathbf{E}$$

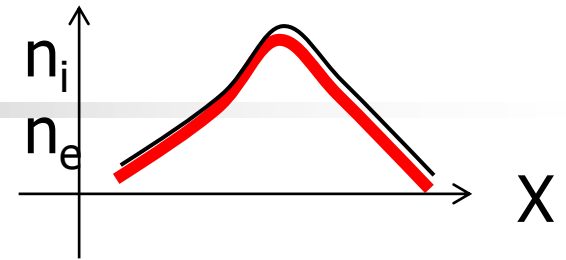
$$= \int \frac{m}{2} c^2 \left(\frac{\delta F_s}{\delta t} \right)_{\text{collision}} d\mathbf{v}$$

s=ion or electron

“closure”

Single-fluid variables

For the macro-scale variables



$$L \gg \lambda_D \quad \omega \ll \omega_p \quad \rightarrow \quad n_e \approx n_i \quad \text{quasi-neutrality 準中性}$$

■ Total mass density

$$\rho(\mathbf{r}, t) = n_e m_e + n_i m_i = n(m_e + m_i) \sim n m_i = \rho_i$$

■ Center of mass velocity

$$\mathbf{u}(\mathbf{r}, t) = \frac{1}{\rho} (n_e m_e \mathbf{u}_e + n_i m_i \mathbf{u}_i) \sim \mathbf{u}_i$$

■ Electric current density

$$\mathbf{J}(\mathbf{r}, t) = e(n_i \mathbf{u}_i - n_e \mathbf{u}_e) \sim -n e u_e$$

Magnetohydrodynamics (MHD) eq.

- Cont. eq.
$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

- Eq. Motion
$$\frac{\partial}{\partial t} (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \mathbf{u}) + \nabla \cdot \tilde{\mathbf{P}} - \mathbf{J} \times \mathbf{B} = \left(\frac{\delta \mathcal{M}}{\delta t} \right)_{collision}$$

- Energy eq.
$$\frac{\partial}{\partial t} \left(\frac{1}{\gamma-1} \tilde{P} + \frac{1}{2} \rho u^2 + \rho U_{grav} + \frac{\epsilon_0}{2} E^2 + \frac{B^2}{2\mu_0} \right) + \nabla \cdot \left\{ \rho \mathbf{u} \left(\frac{\gamma}{\gamma-1} \frac{P}{\rho} + \frac{1}{2} u^2 + U_{grav} \right) + \frac{\mathbf{E} \times \mathbf{B}}{\mu_0} + \mathbf{Q} \right\} = -\mathbf{J} \cdot \mathbf{E} + \int \frac{m}{2} c^2 \left(\frac{\delta F_s}{\delta t} \right)_{collision} d\mathbf{v}$$

- Generalized Ohm's law

$$\mathbf{E} = -\mathbf{u} \times \mathbf{B} + \eta \mathbf{J}$$

Faraday's law

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$

Ampere's law

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$

Hierarchy of Plasma equations

long
large

■ Macro-scale

■ Magneto-hydrodynamic (MHD) eq. $f(r)$

- Single fluid model



quasi-neutral

- Two-fluid model

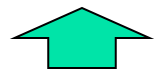


velocity space moment

■ Micro-scale

■ Kinetic model

- $F(r, v)$



ensemble average

- $\hat{F}(r_i, v_i)$

short
small

$$\begin{aligned}\frac{\partial \mathbf{B}}{\partial t} &= -\nabla \times \mathbf{E} \\ \nabla \cdot \mathbf{B} &= 0 \\ \nabla \cdot \mathbf{E} &= \frac{\rho}{\epsilon_0} \\ \nabla \times \mathbf{B} &= \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}\end{aligned}$$

Maxwell eq.

Scales

- Gyro-radius

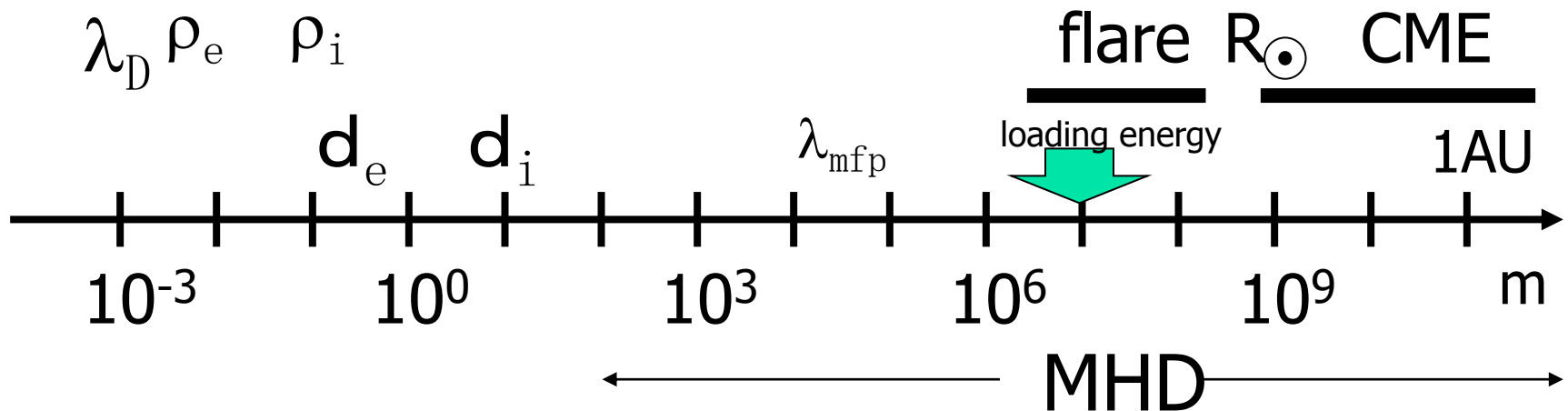
$$\rho_s = \frac{v_{th}}{\omega_{s,gyro}} \quad \omega_{s,gyro} = \frac{eB}{m_s}$$

- Skin length

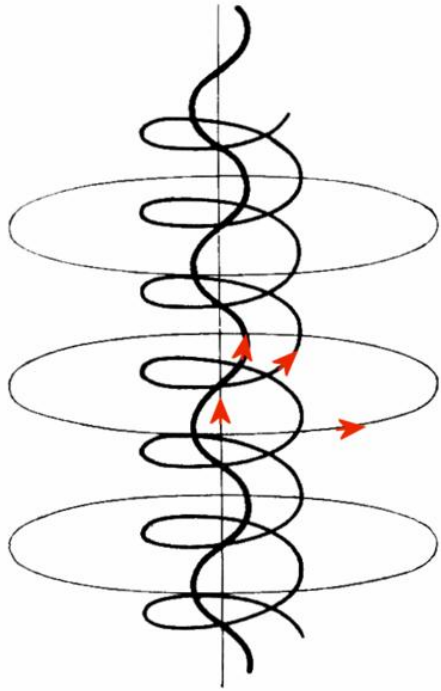
$$d_s = \frac{c}{\omega_{ps}} \quad \omega_{ps} = \sqrt{\frac{ne^2}{m_s \epsilon_0}}$$

- Debye length

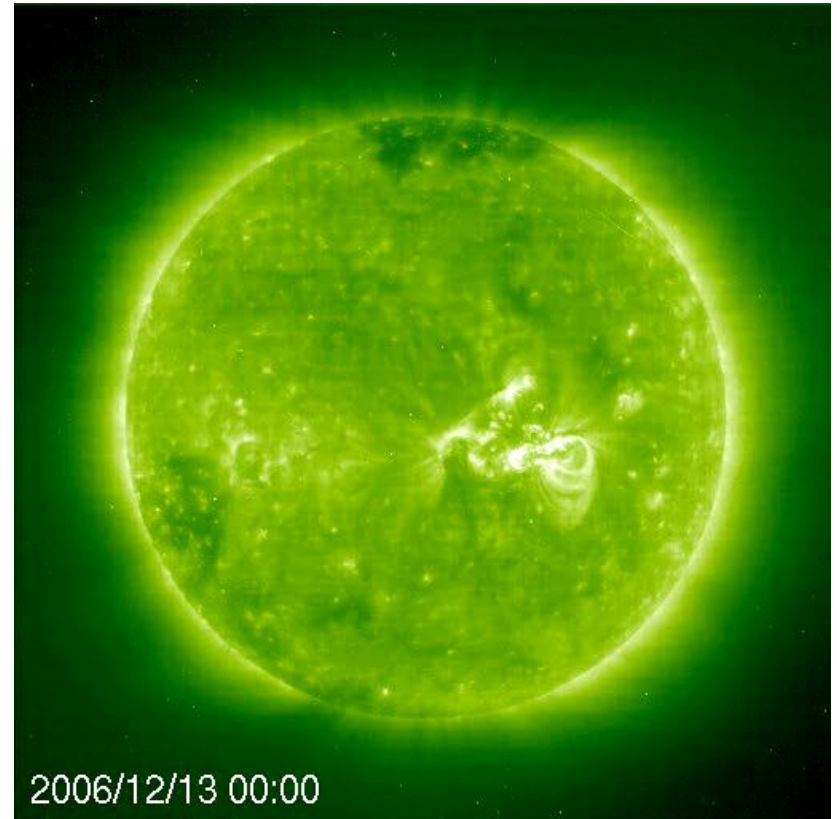
$$\lambda_D = \sqrt{\frac{\epsilon_0 kT}{2ne^2}}$$



Scales in the solar coronal plasma

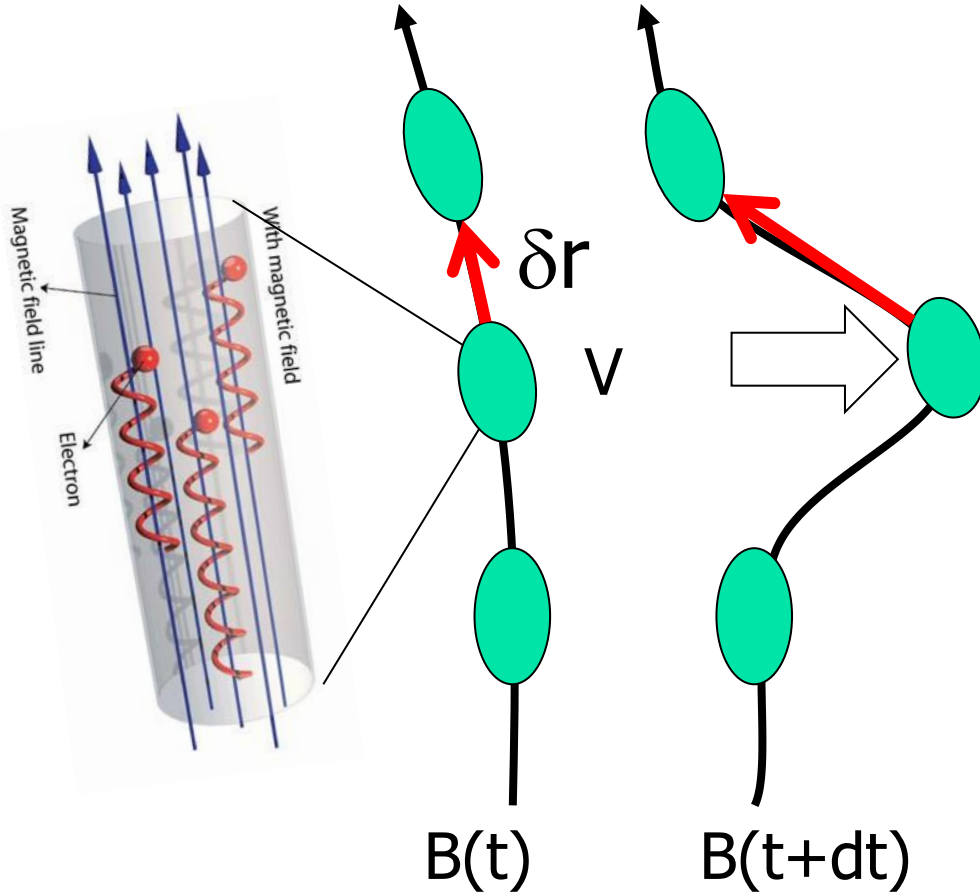


$$r_i \sim 1 \text{ m}, \omega_{gi} \sim 10^6$$
$$r_e \sim 2 \times 10^{-2} \text{ m}, \omega_{ge} \sim 10^9$$



$$R_{\text{sun}} \sim 7.0 \times 10^8 \text{ m}$$

“凍結 (frozen-in)”



Ideal MHD eq.

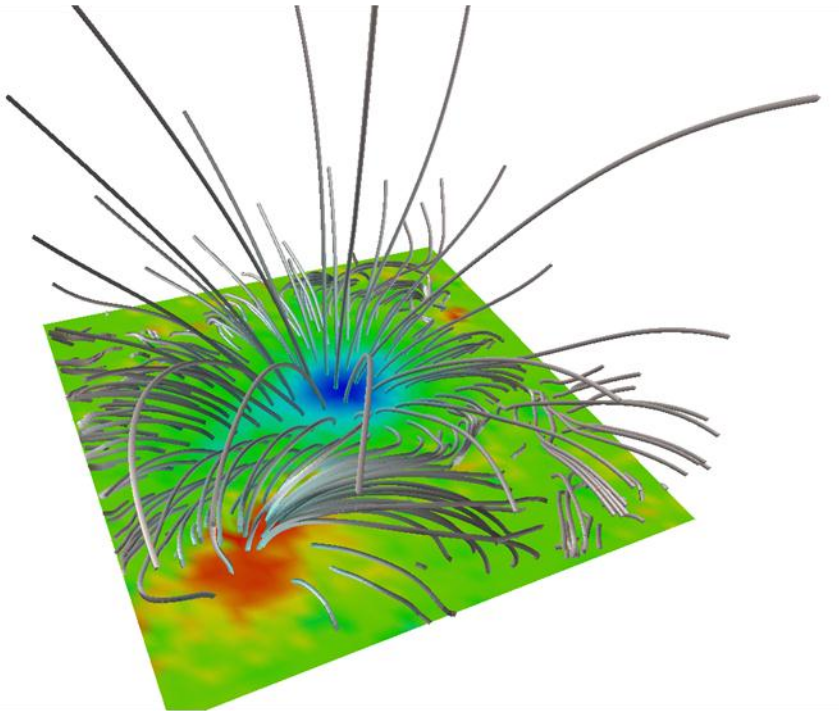
$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{V} \times \mathbf{B} - \eta \mathbf{J})$$

$$\frac{d}{dt} \left(\frac{\mathbf{B}}{\rho} \right) = \left(\frac{\mathbf{B}}{\rho} \cdot \nabla \right) \mathbf{V}$$

↕ Same eq.

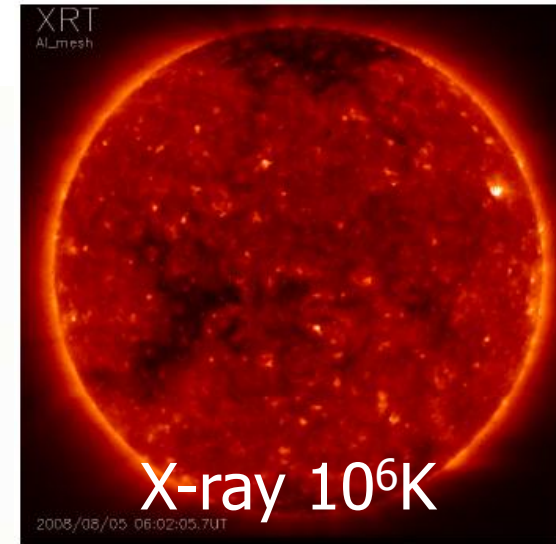
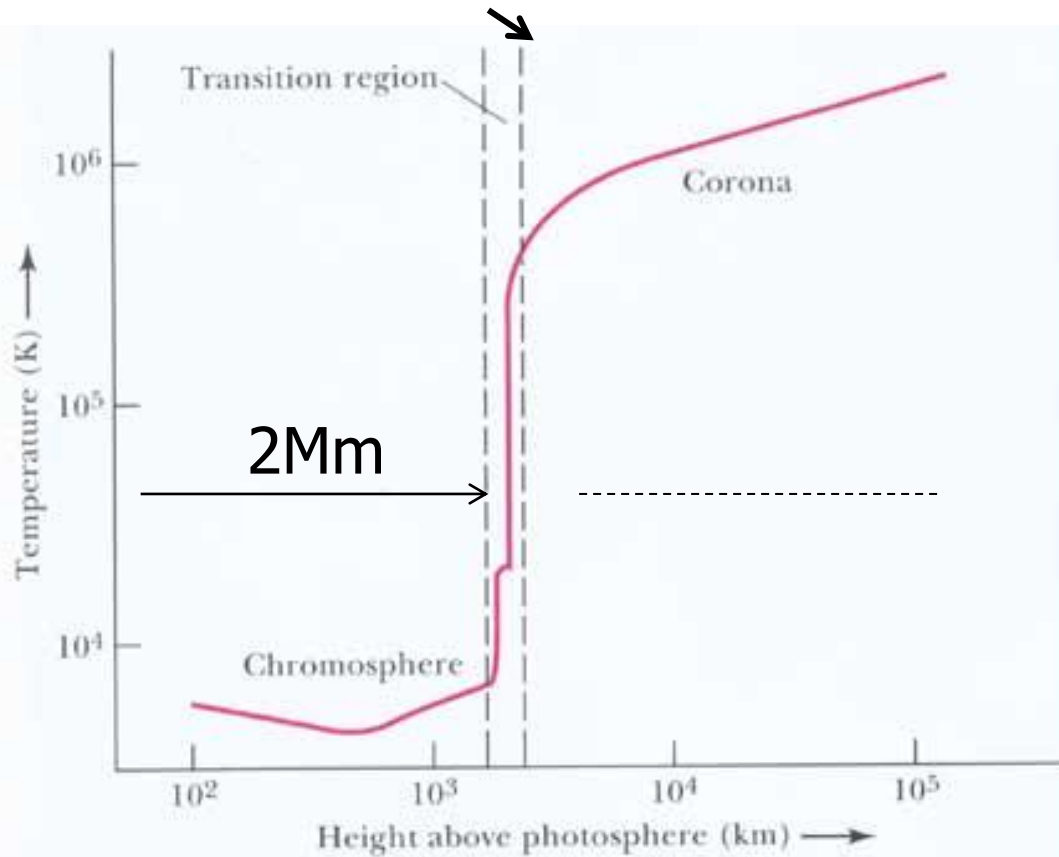
$$\frac{d}{dt} (\delta \mathbf{r}) = (\delta \mathbf{r} \cdot \nabla) \mathbf{V}$$

Magnetic Structure in Solar Active Regions



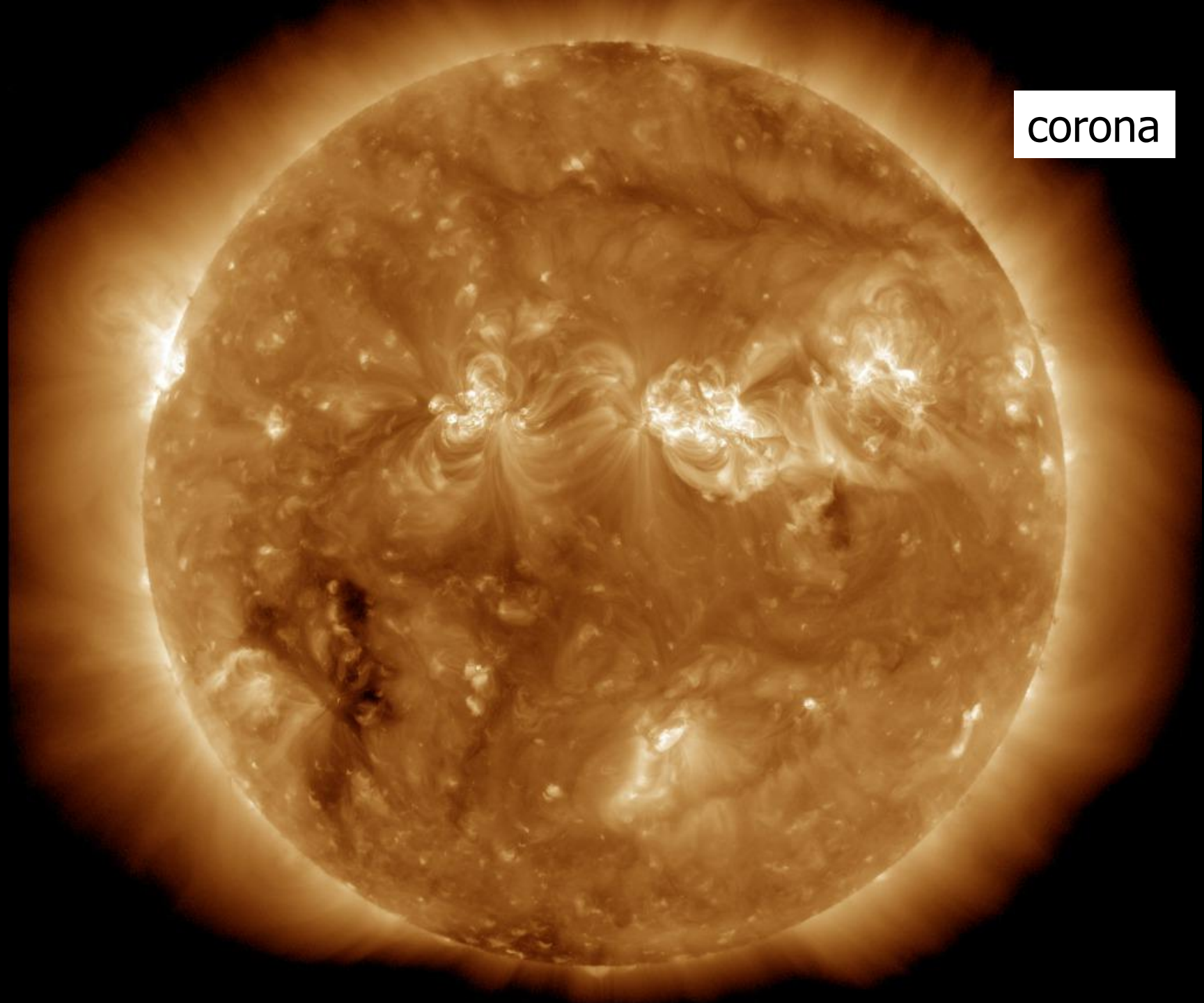
Solar Atmosphere

- Multi-layer Structure

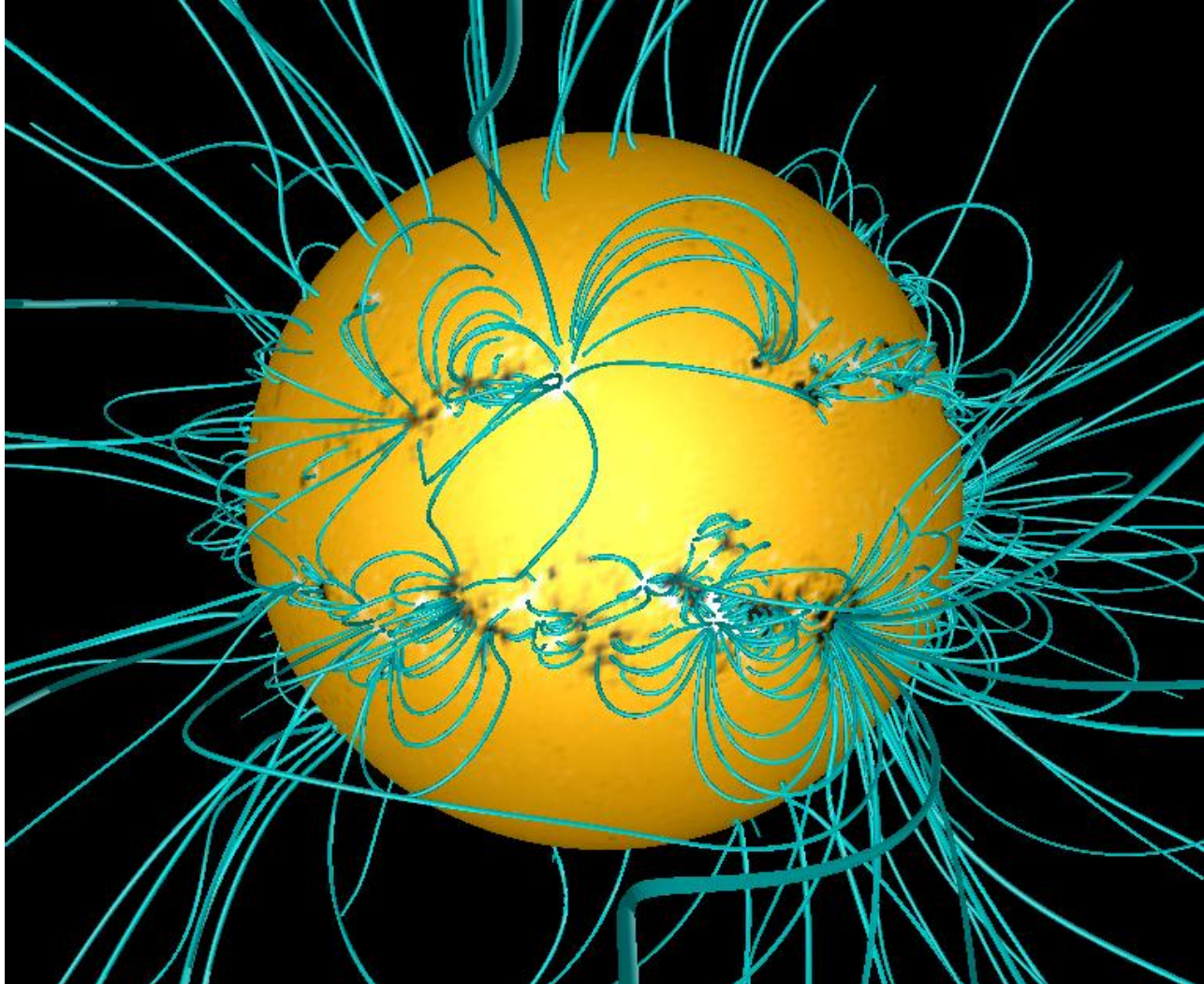


white light 6×10^3 K

corona



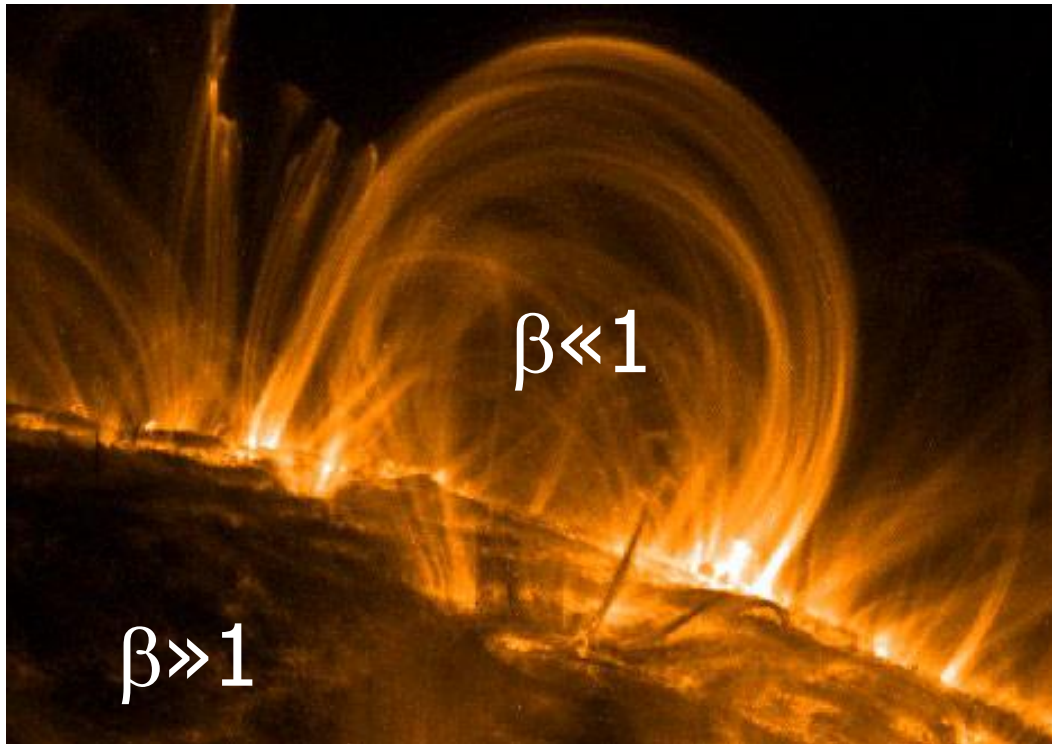
Magnetic Structure



open field

closed field

Plasma β ratio



$$\beta = \frac{\text{plasma pressure}}{\text{magnetic pressure}}$$
$$= \frac{p}{\frac{B^2}{2\mu_0}}$$

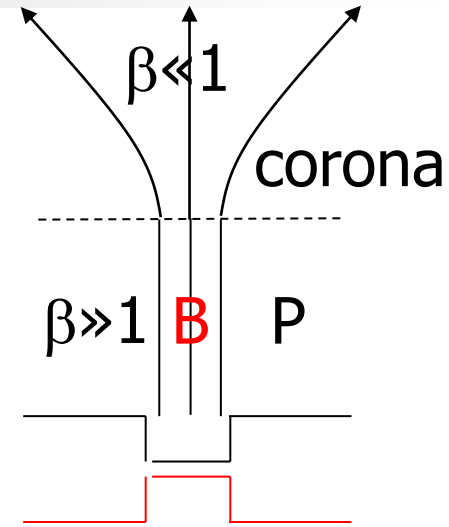
MHD Equilibrium

$$\frac{\partial}{\partial t}(\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \mathbf{u}) = \mathbf{J} \times \mathbf{B} - \nabla \cdot \tilde{\mathbf{P}}$$

$$\mathbf{F} = \mathbf{J} \times \mathbf{B} - \nabla P = (B \cdot \nabla) \mathbf{B} - \nabla \left(\frac{B^2}{2\mu_0} + p \right) = 0$$

$$\mathbf{J} = \mathbf{J}_{\parallel} + \frac{\mathbf{B} \times \nabla P}{B^2}$$

- Force-Free Field ($\beta \ll 1$) $\mathbf{J} \times \mathbf{B} = 0, \nabla P = 0$
 $\mathbf{J} = \mathbf{J}_{\parallel} \Rightarrow \nabla \times \mathbf{B} = \alpha \mathbf{B}$



- Nonlinear Force-Free Field

- Linear Force-Free Field

- Potential Field

$$\mathbf{B} \cdot \nabla \alpha = 0$$

$$\nabla \alpha = 0$$

$$\alpha = 0 \quad (B = -\nabla \varphi)$$

Linear Force Free Field

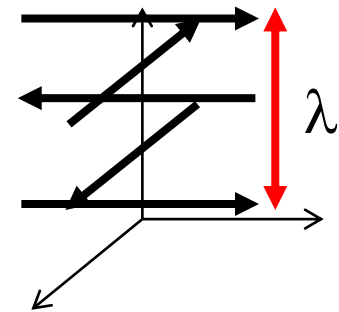
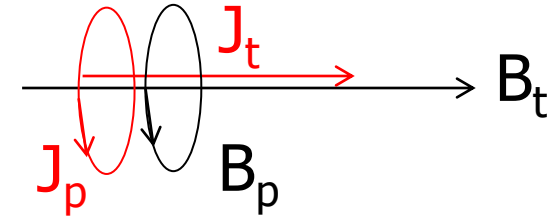
$$\nabla \times \mathbf{B} = \alpha \mathbf{B} \quad \text{where } \alpha = \alpha_0 \text{ (const.)}$$

$$\alpha = 2\pi / \lambda$$

■ Rectangle system

$$\mathbf{B} = B_0 (\cos \alpha z, -\sin \alpha z, 0)$$

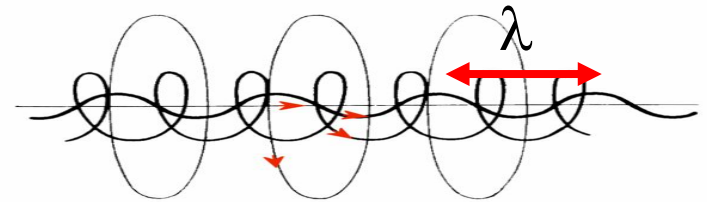
$$\nabla \times \mathbf{B} = \alpha B_0 (\cos \alpha z, -\sin \alpha z, 0) = \alpha \mathbf{B}$$

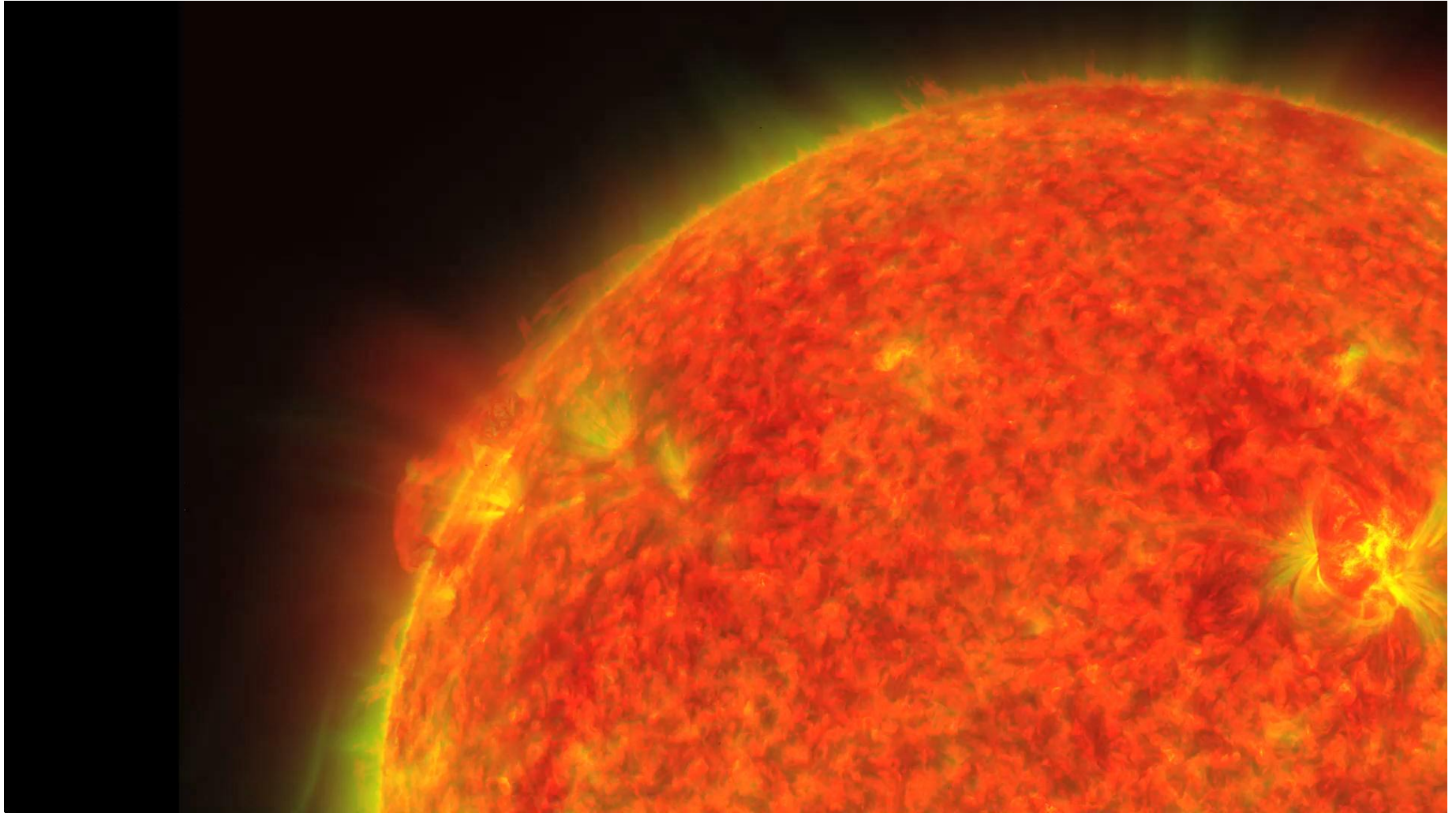


■ Cylindrical system

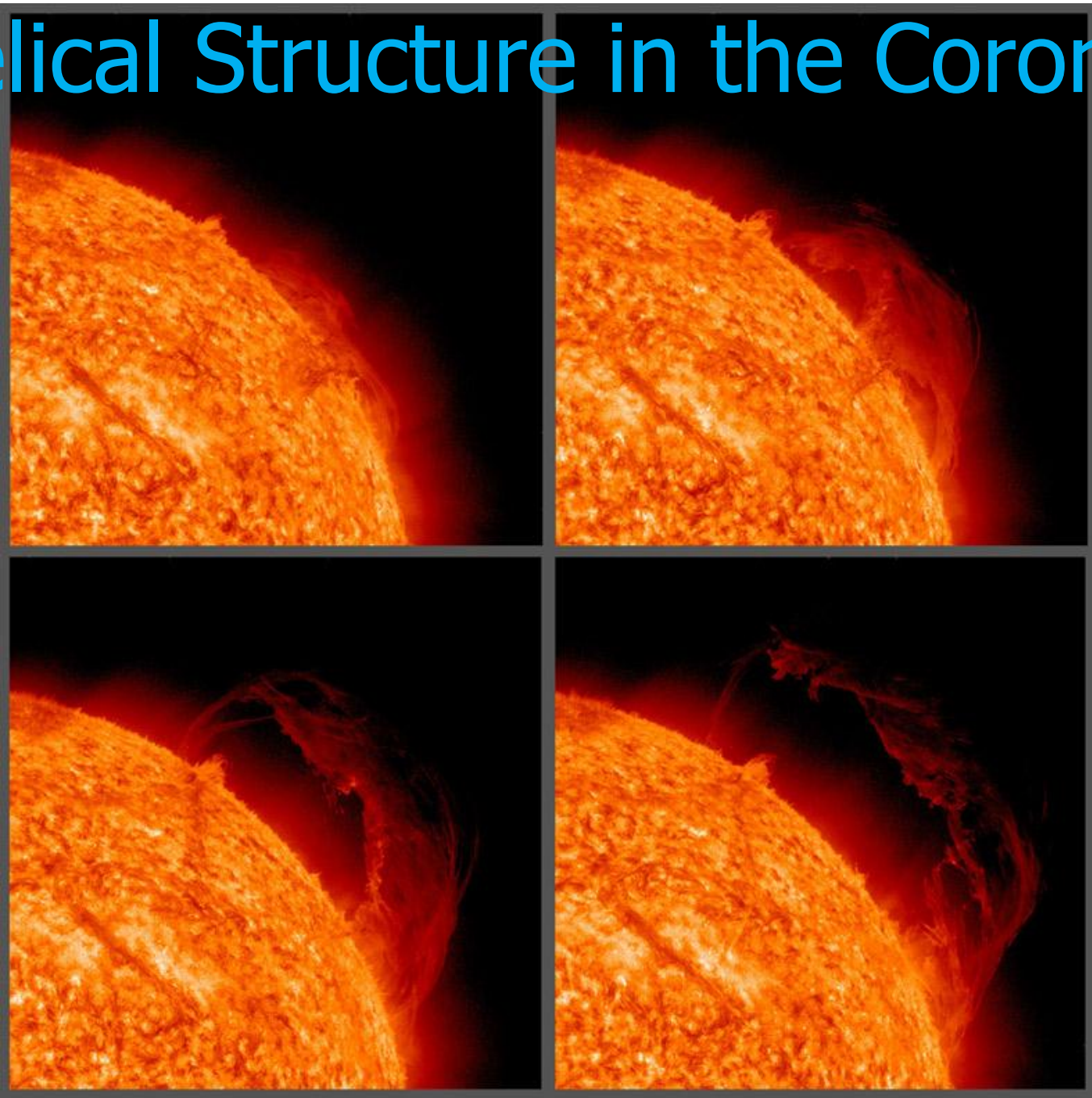
$$\mathbf{B} = B_0 (0, J_1(\alpha r), J_0(\alpha r))$$

$$\nabla \times \mathbf{B} = \left(0, -\frac{\partial B_z}{\partial r}, \frac{1}{r} \frac{\partial}{\partial r} (r B_\phi)\right) = \alpha B_0 (0, J_1(\alpha r), J_0(\alpha r))$$



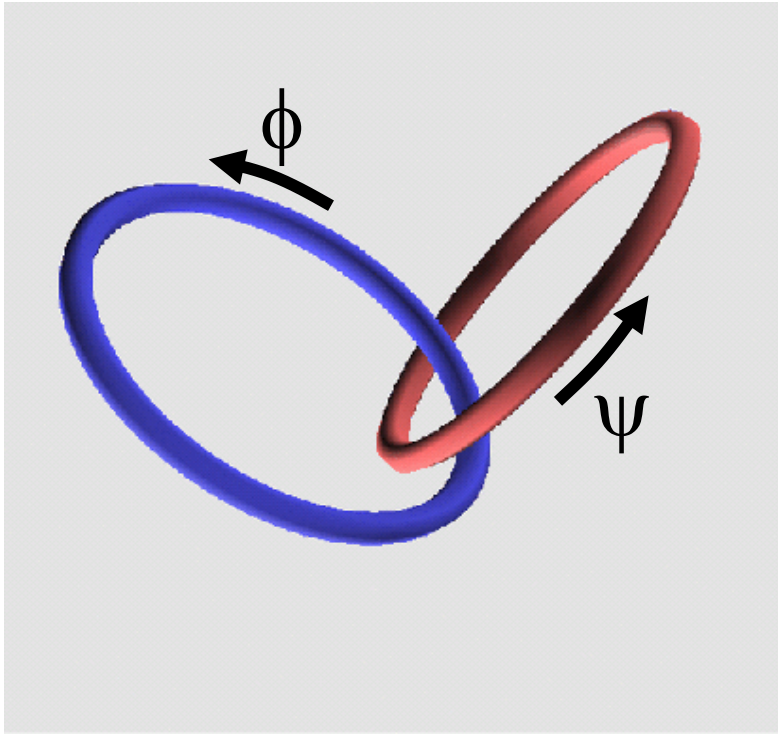


Helical Structure in the Corona

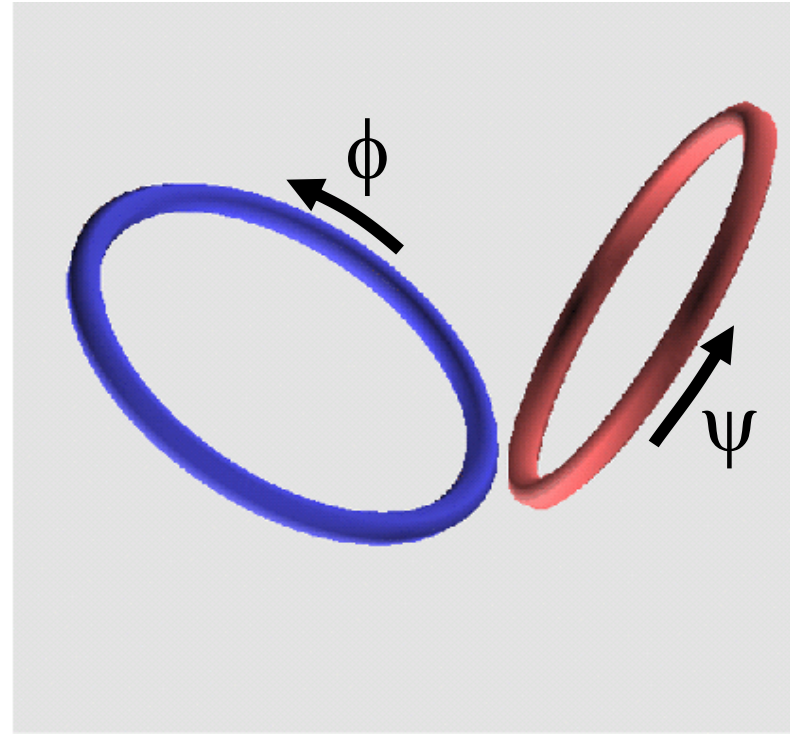


Magnetic Helicity (field linkage)

$$H = \int \mathbf{A} \cdot \mathbf{B} dV$$



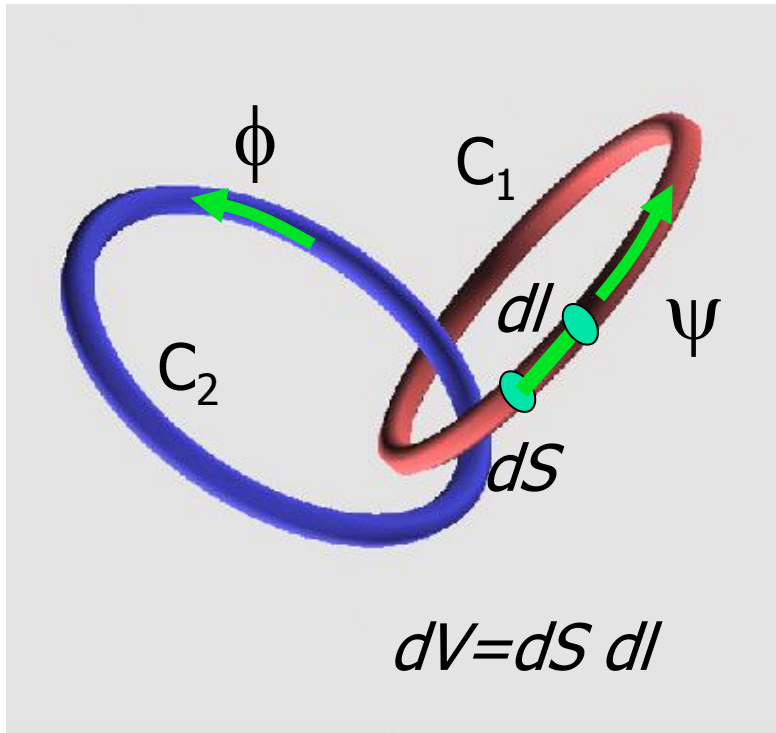
$$H=2\phi\psi$$



$$H=0$$

Helicity is a topological invariant.

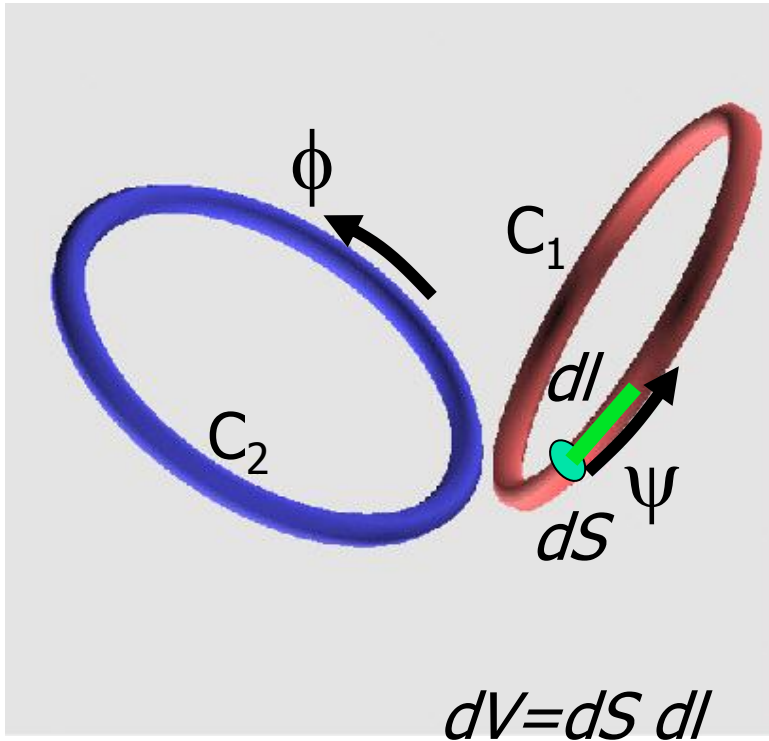
- Linking Fluxes



$$\begin{aligned}
 H &= \int \mathbf{A} \cdot \mathbf{B} dV \\
 &= \oint_{C_1} \mathbf{A} \cdot d\mathbf{l} \int \mathbf{B} \cdot d\mathbf{S} \\
 &\quad + \oint_{C_2} \mathbf{A} \cdot d\mathbf{l} \int \mathbf{B} \cdot d\mathbf{S} \\
 &= \phi \quad \psi \\
 &\quad + \quad \psi \quad \phi \\
 &= 2\psi\phi
 \end{aligned}$$

Helicity is a topological invariant.

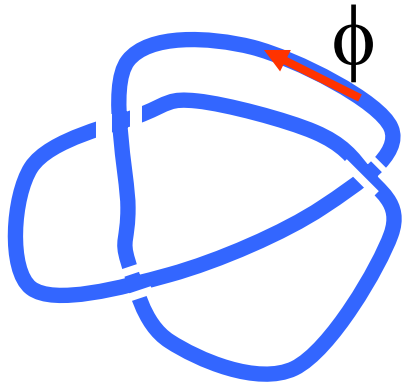
- Not Linking Fluxes



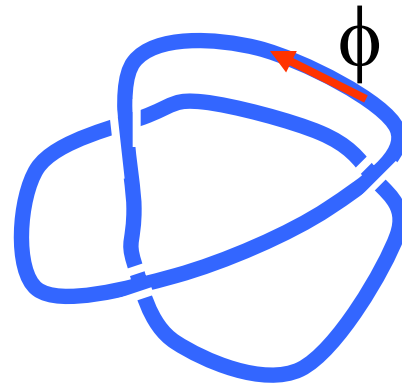
$$\begin{aligned}
 H &= \int \mathbf{A} \cdot \mathbf{B} dV \\
 &= \oint_{C_1} \mathbf{A} \cdot d\mathbf{l} \int \mathbf{B} \cdot d\mathbf{S} \\
 &\quad + \oint_{C_2} \mathbf{A} \cdot d\mathbf{l} \int \mathbf{B} \cdot d\mathbf{S} \\
 &= 0 \quad \psi \\
 &\quad + 0 \quad \phi \\
 &= 0
 \end{aligned}$$

Questions

Calculate the magnetic helicity of these flux tubes.



$$H=2\phi^2$$



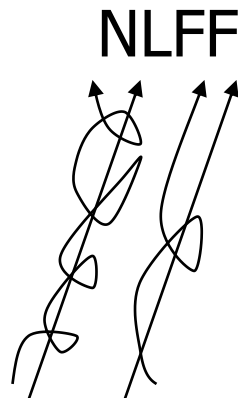
$$H=0$$

- Magnetic helicity is a topological invariant.
- Magnetic helicity is conserved in the ideal MHD systems.

Taylor's minimum energy state

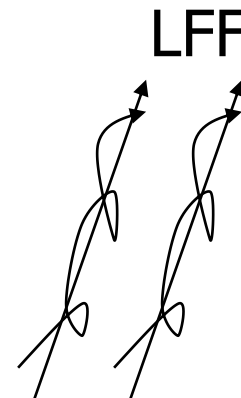
- When mag. helicity is approximately conserved in the resistive MHD system, the minimum energy state is given by a linear force-free field.

$$\begin{array}{l} \text{minimize : } E = \int \mathbf{B} \cdot \mathbf{B} dV \\ \text{invariance : } H = \int \mathbf{A} \cdot \mathbf{B} dV \end{array} \quad \left. \vphantom{\begin{array}{l} \text{minimize} \\ \text{invariance} \end{array}} \right\} \nabla \times \mathbf{B} = \alpha \mathbf{B}$$



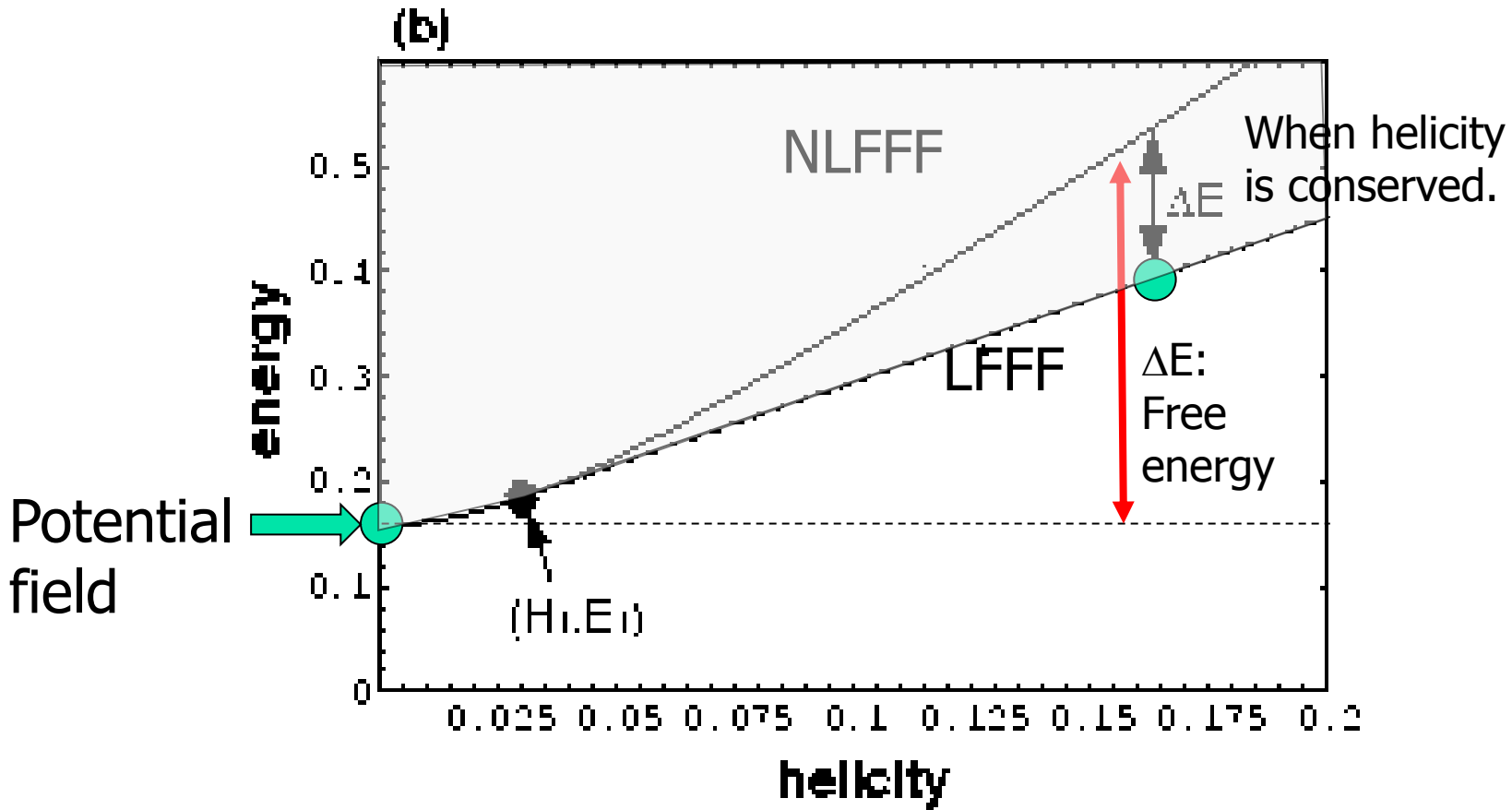
large helicity
(large α)

small helicity
(small α)



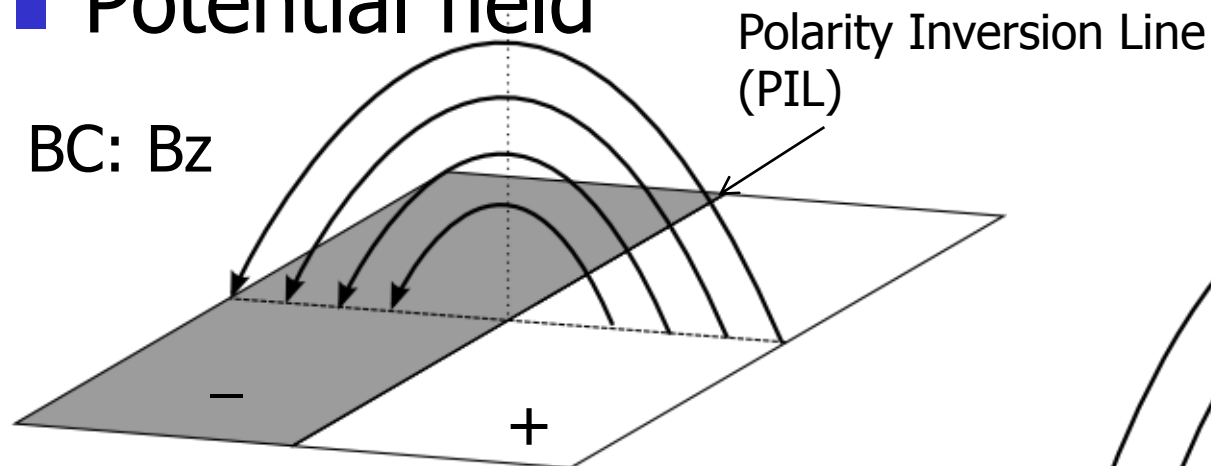
Taylor's minimum energy state

Magnetic Free Energy

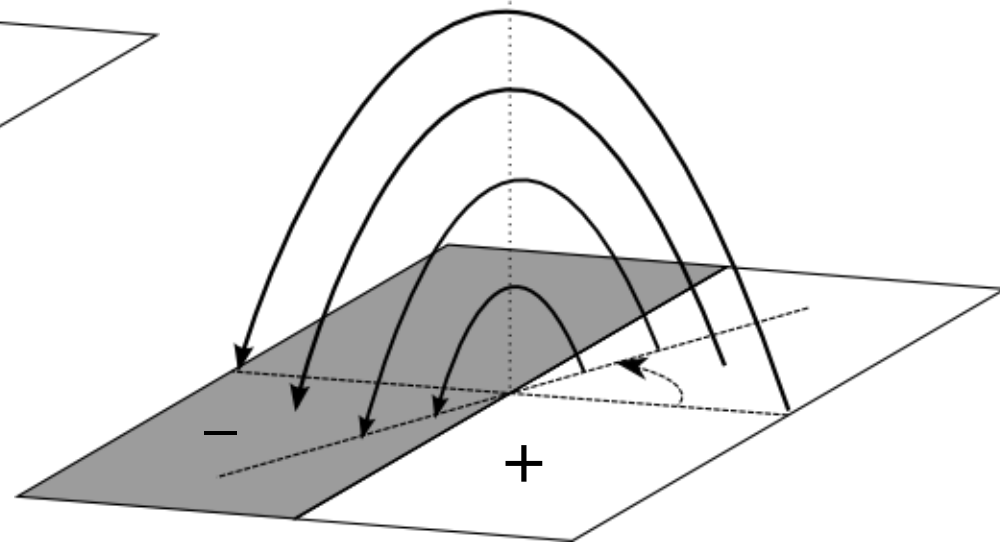


Force-Free Field in the Corona

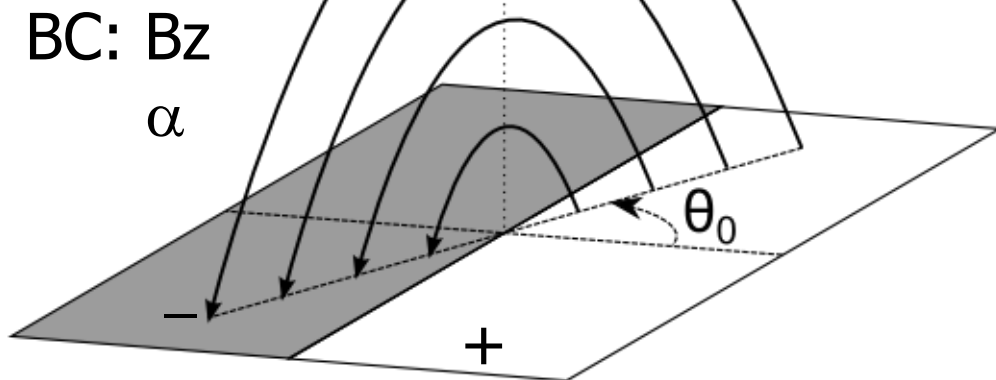
■ Potential field



NLFFF

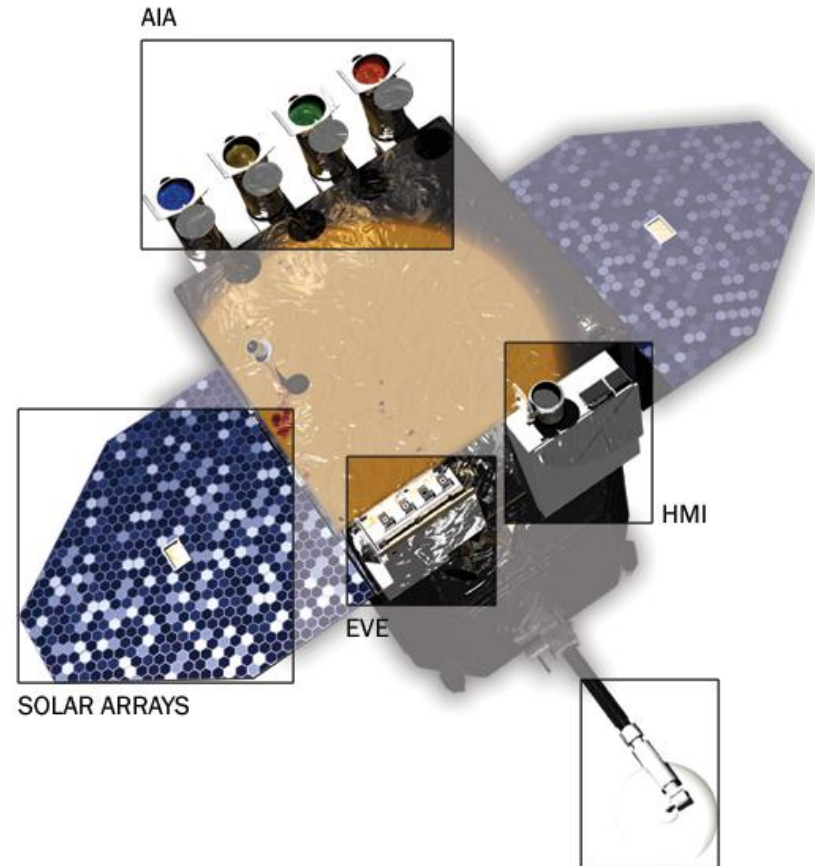
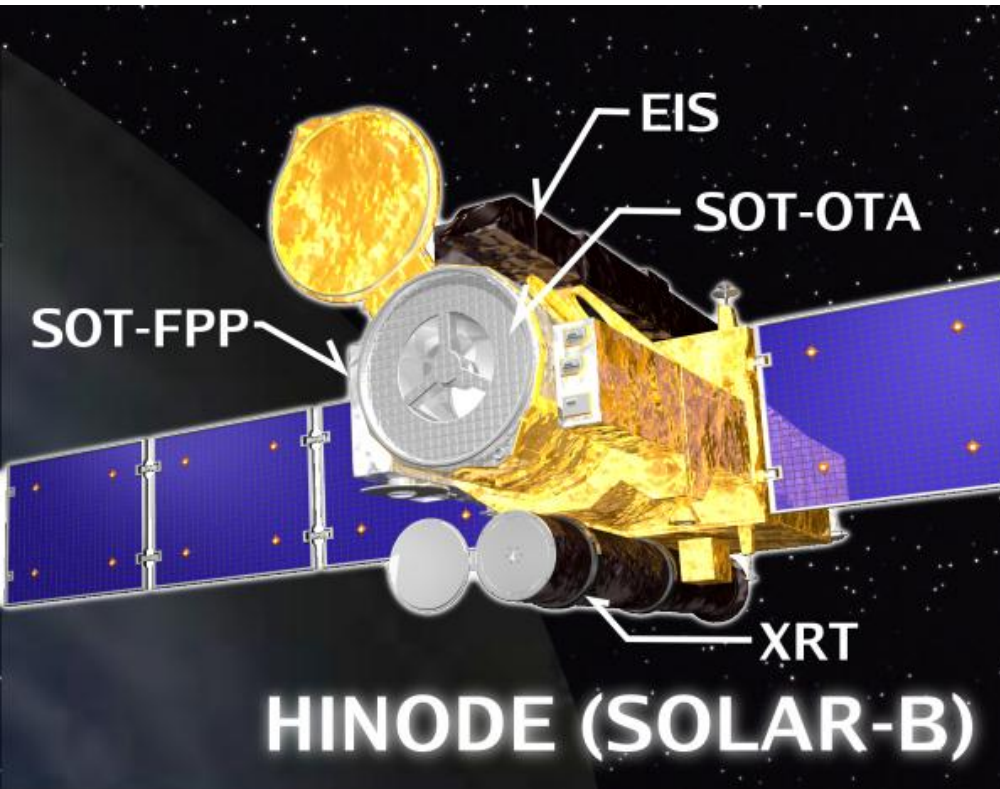


■ LFFF



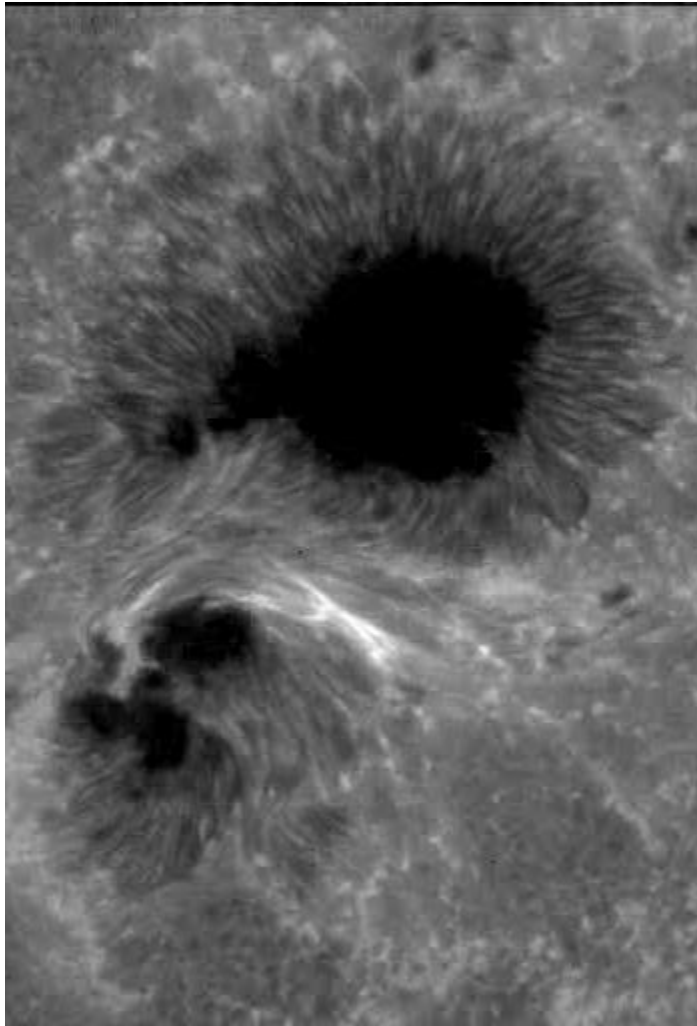
BC: B_x, B_y, B_z

Solar Observatories in Space

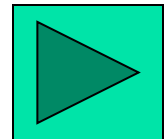
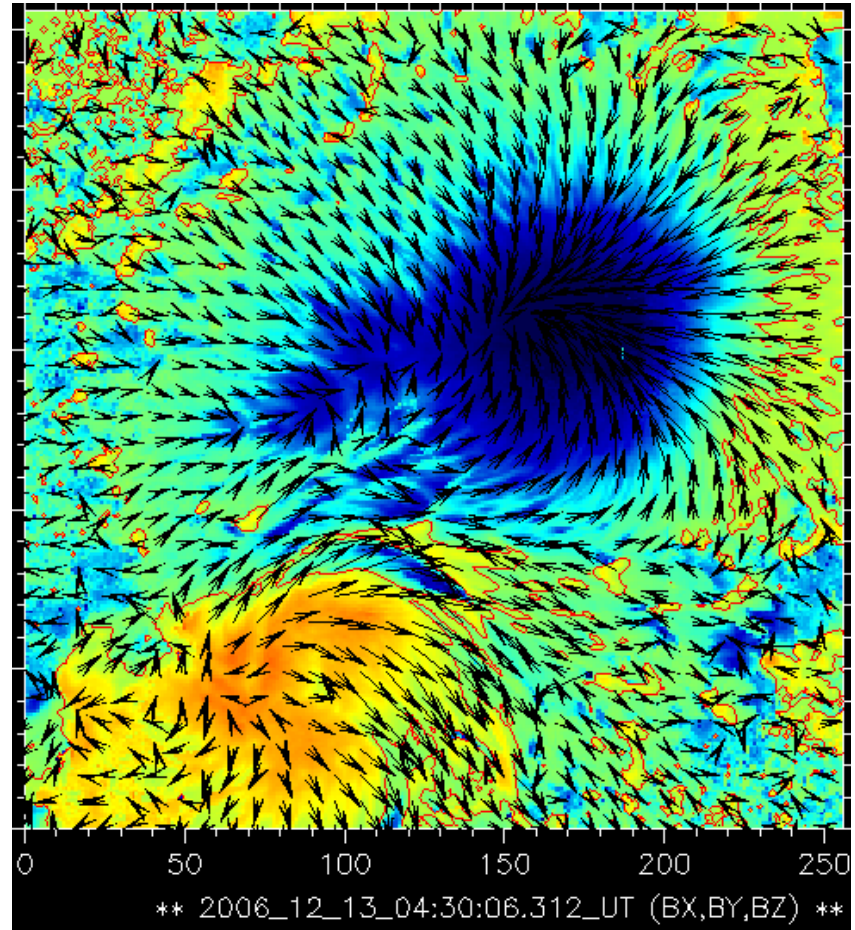


Solar Dynamic Observatory (SDO)

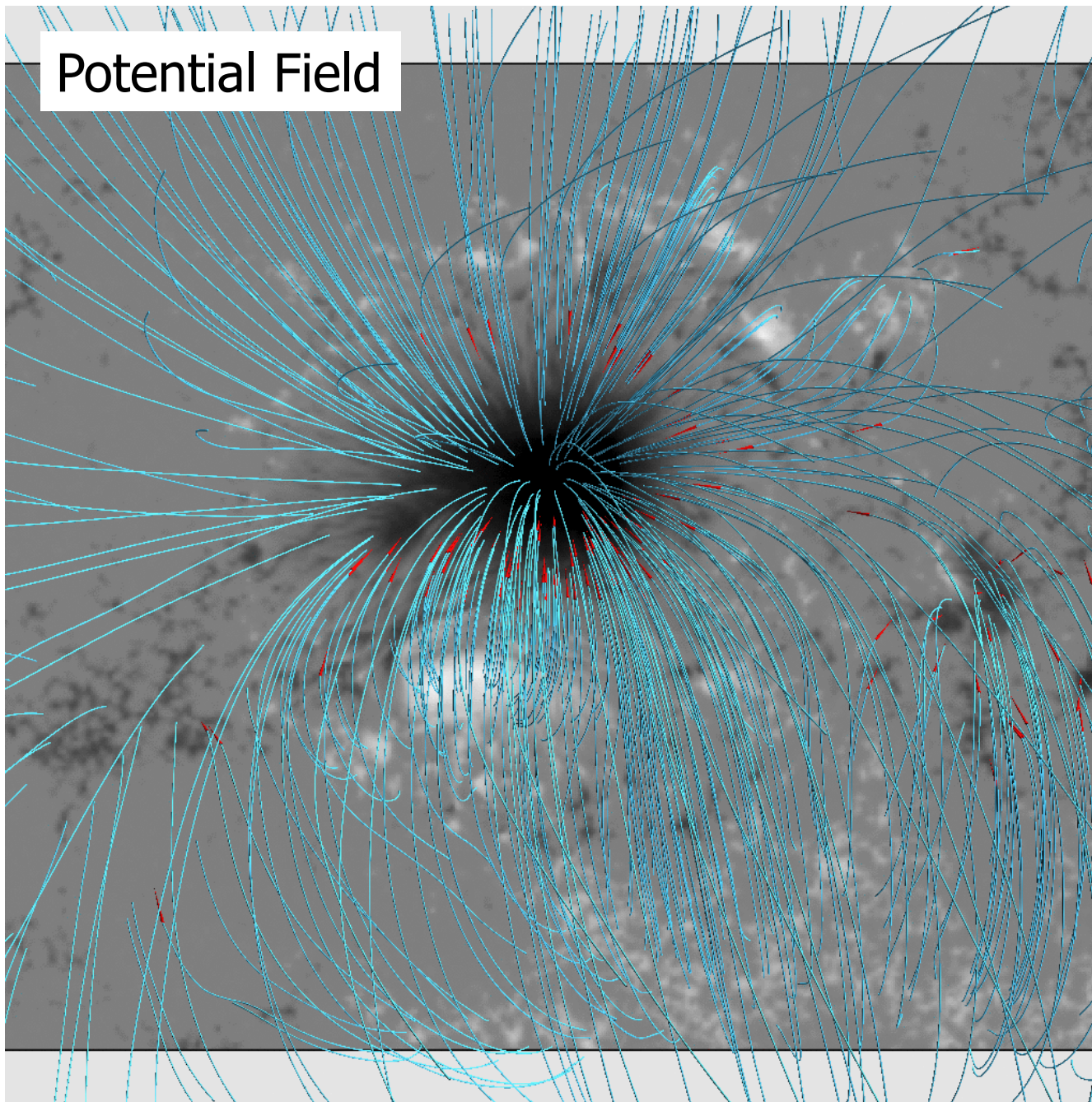
Magnetograph of NOAA10930



2006.12.13 01:42:37

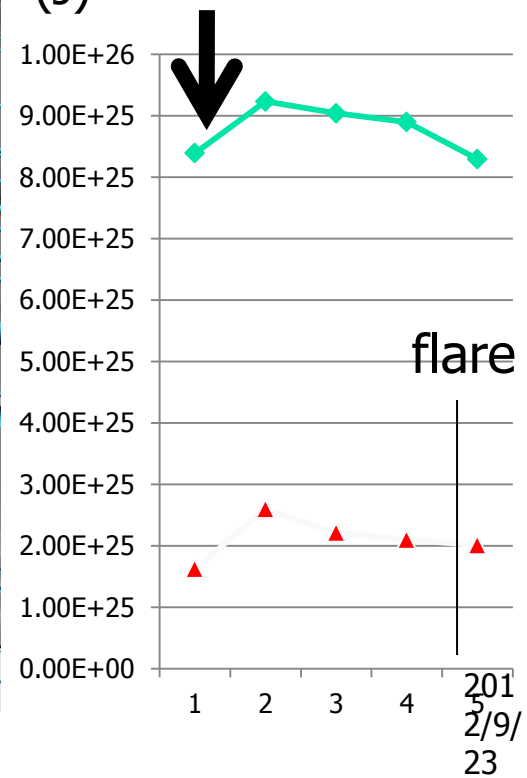


Potential Field



2006_12_11
17:00 UT

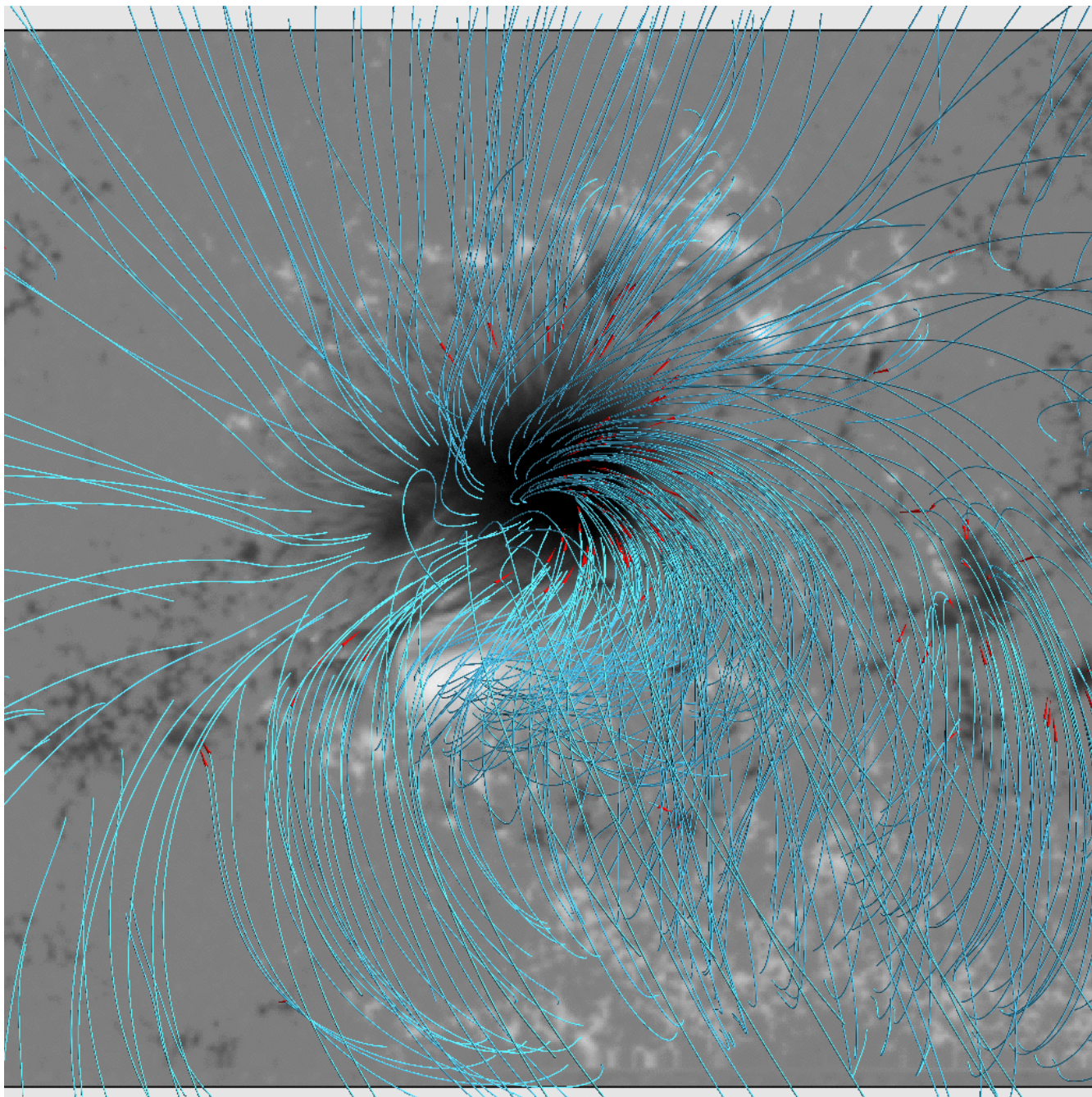
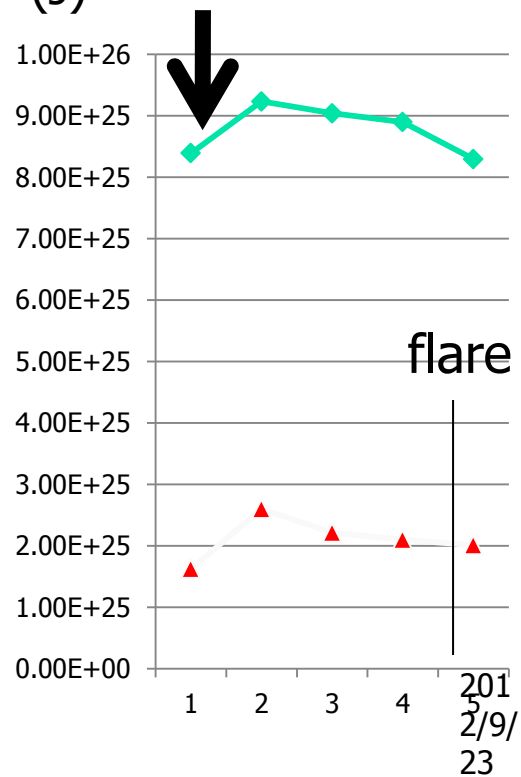
Total Magnetic Energy
Magnetic Free Energy
(J)



33h prior to
flare

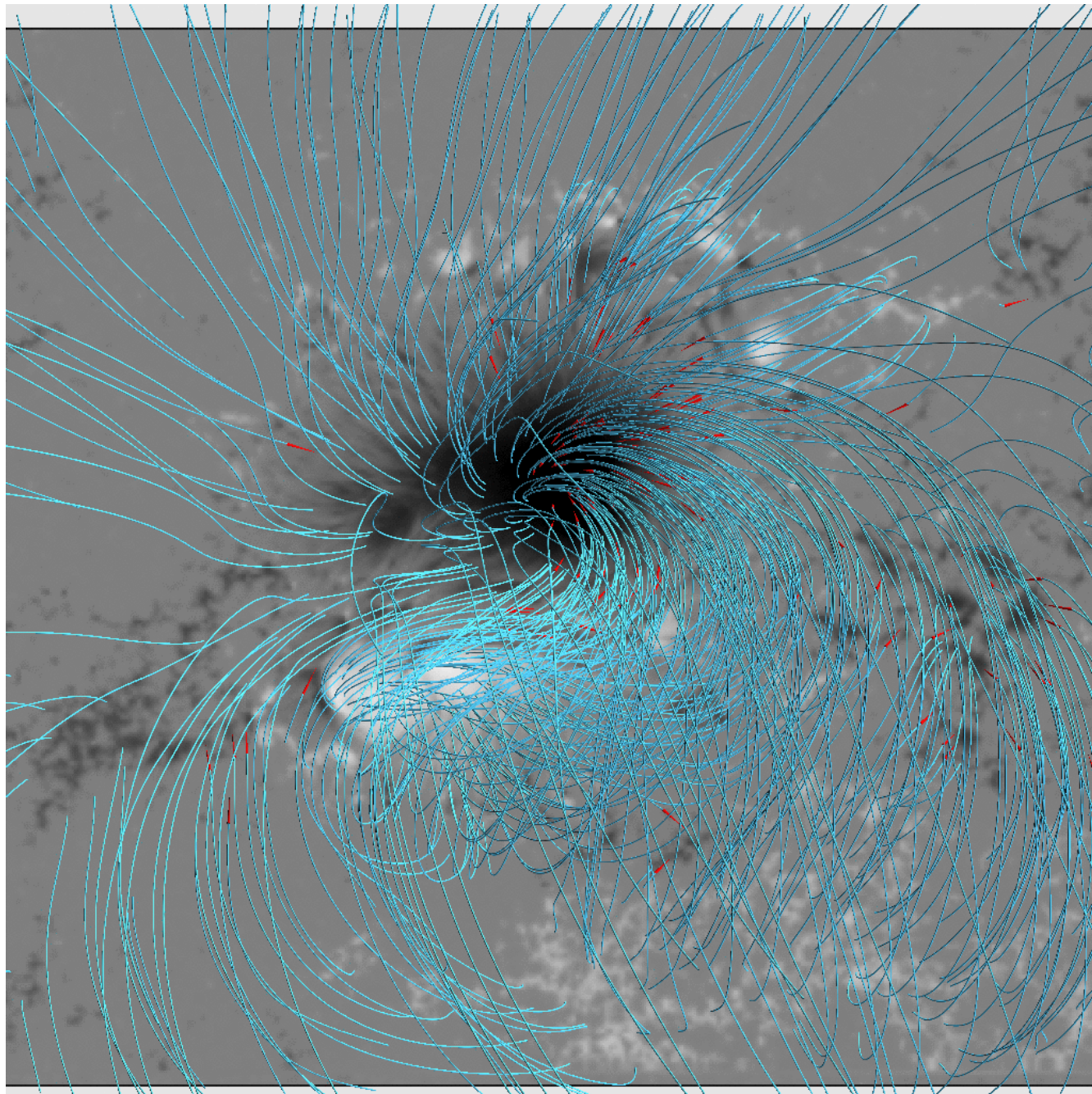
2006_12_11
17:00 UT

Total Magnetic Energy
Magnetic Free Energy
(J)

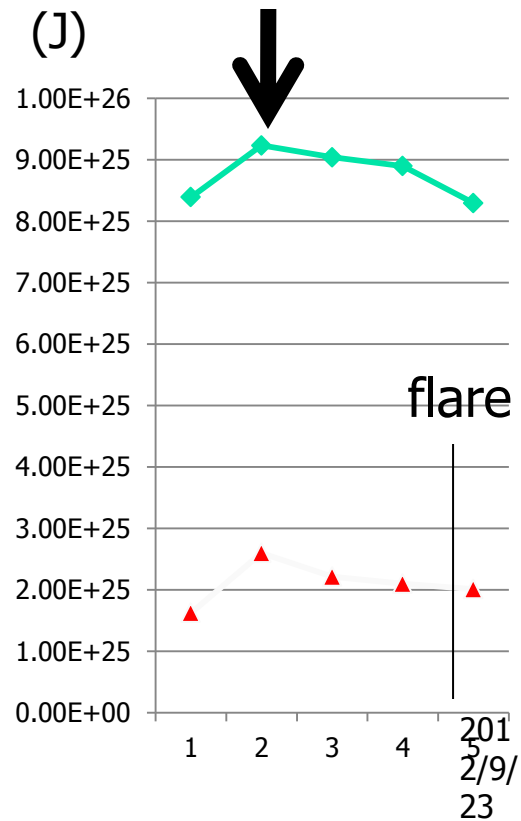


21h prior to
flare

2006_12_12
03:50 UT



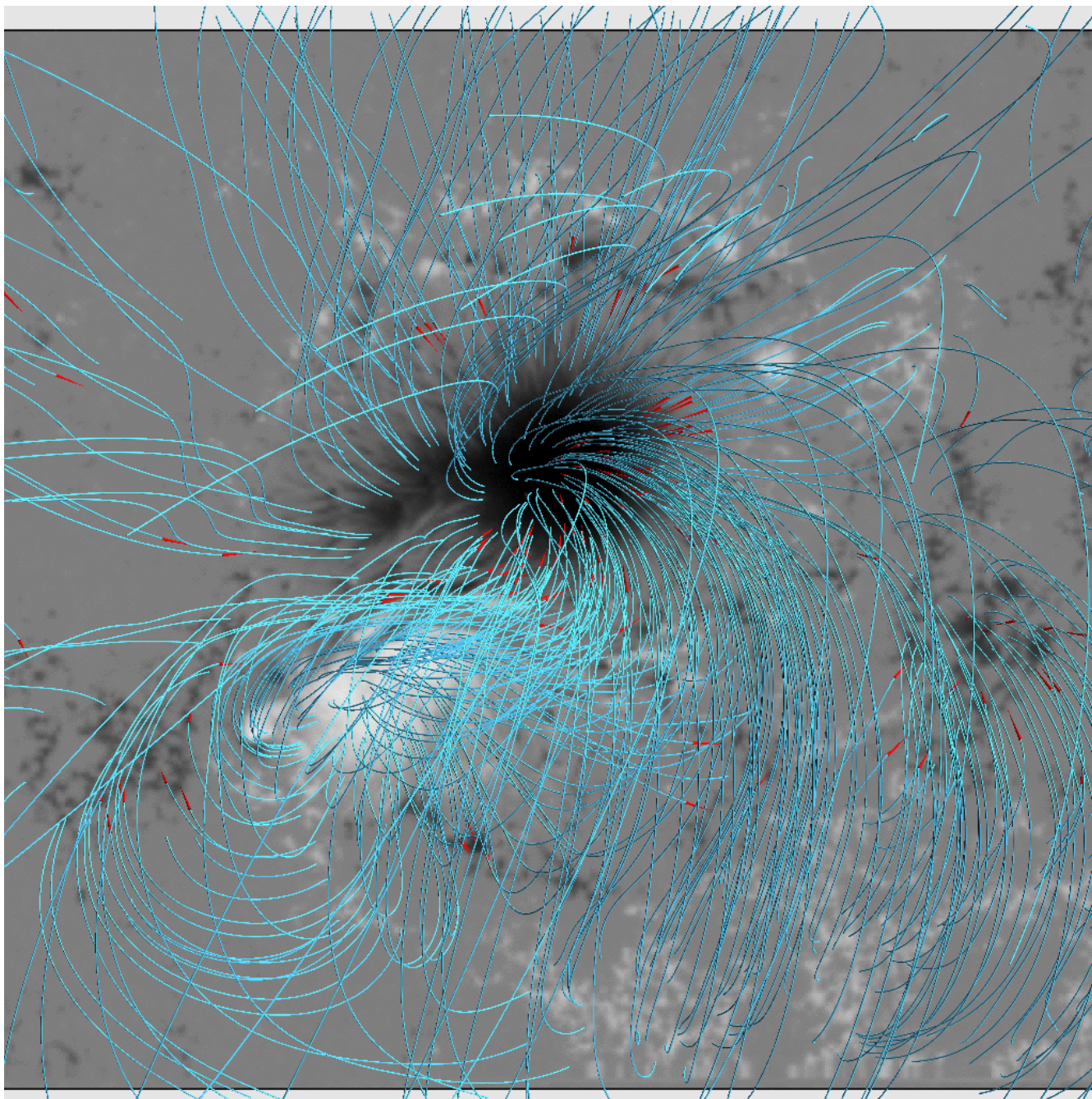
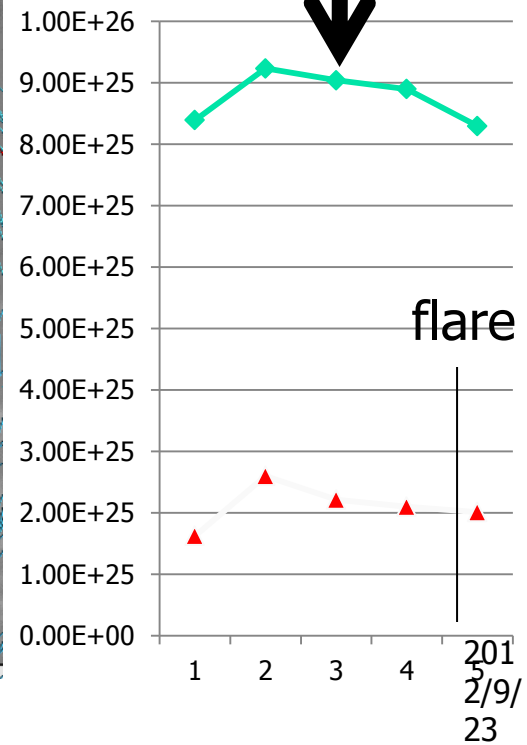
Total Magnetic Energy
Magnetic Free Energy
(J)



8h prior to flare

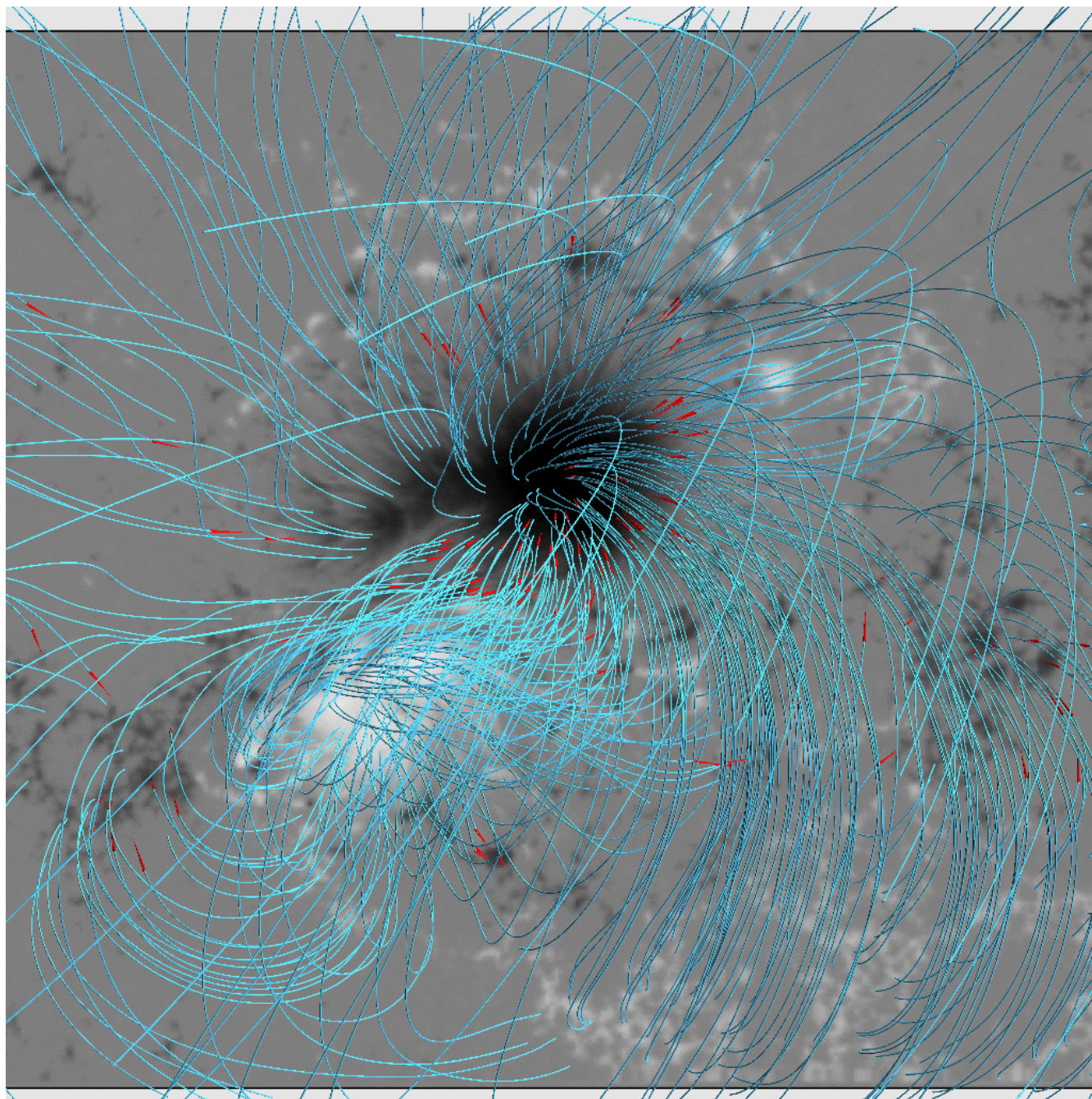
2006_12_12
17:40 UT

Total Magnetic Energy
Magnetic Free Energy
(J)

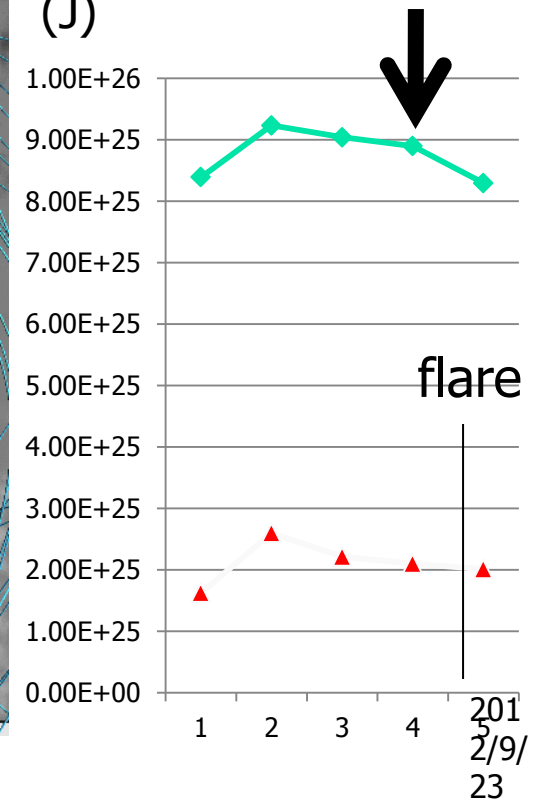


5h after flare

2006_12_12
20:30 UT

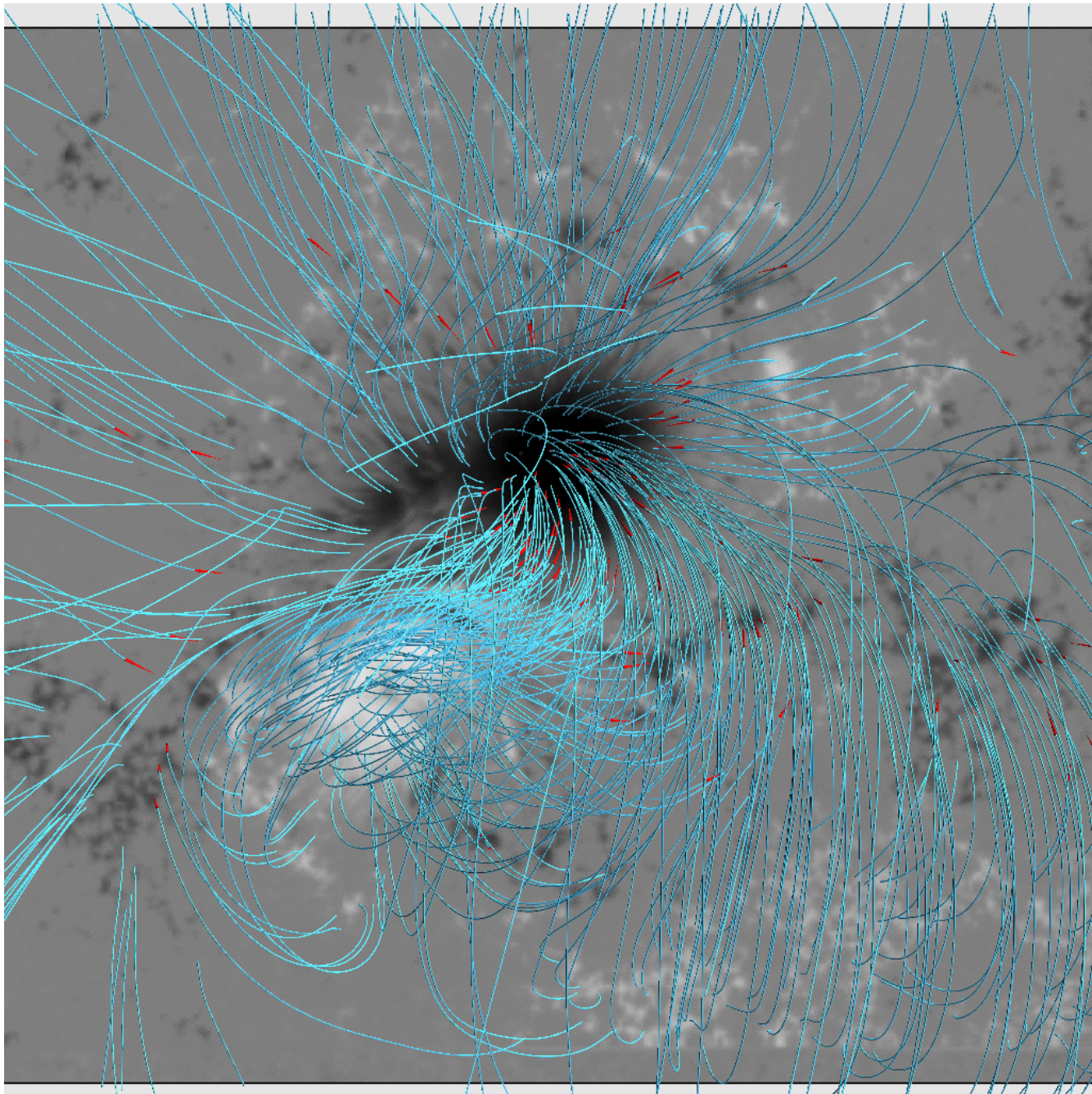


Total Magnetic Energy
Magnetic Free Energy
(J)

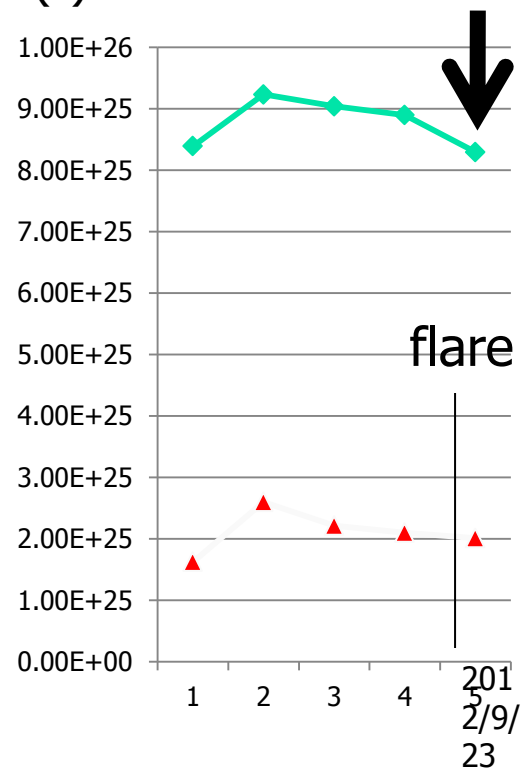


フレア発生
5時間後

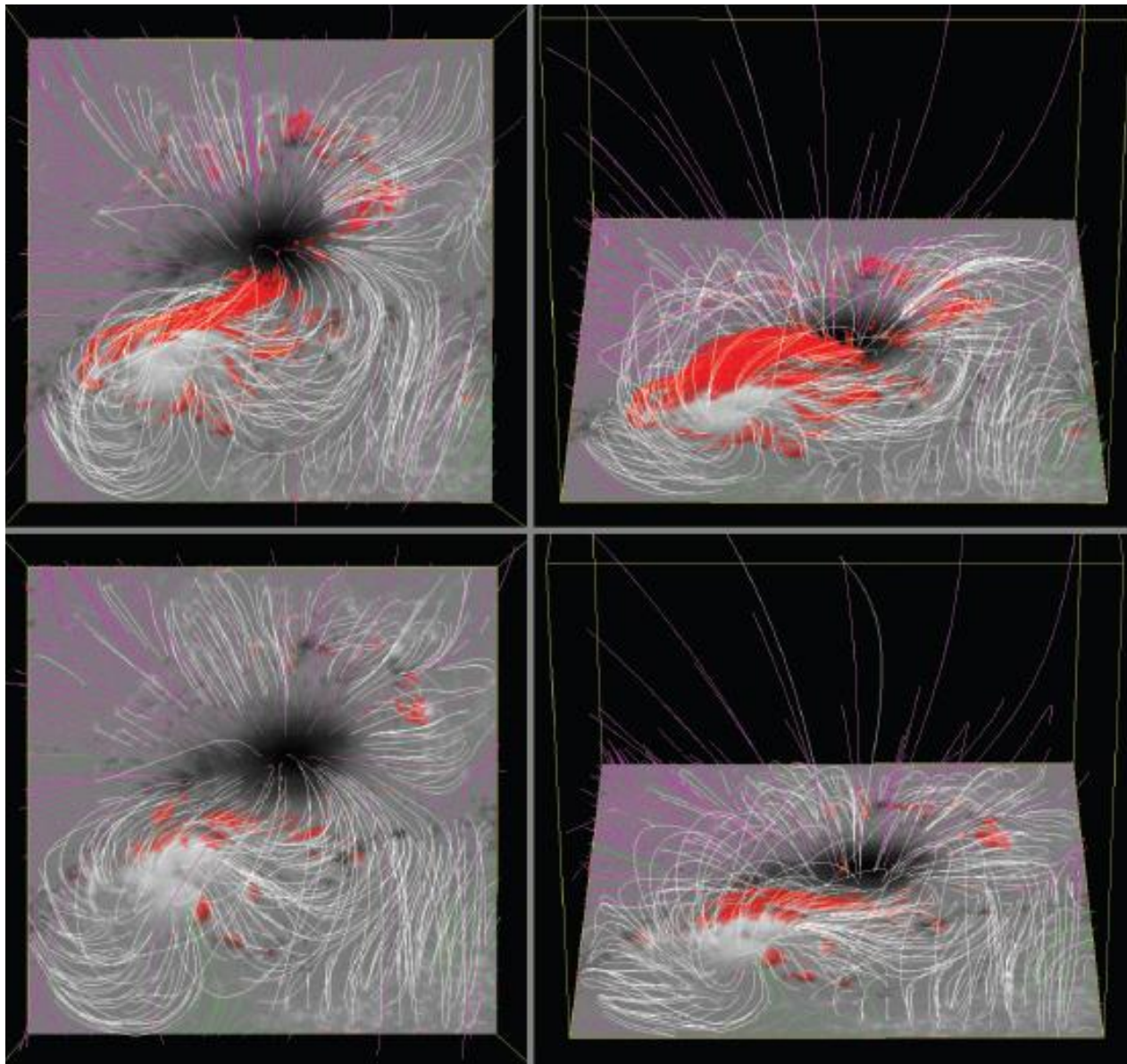
2006_12_13
07:00 UT



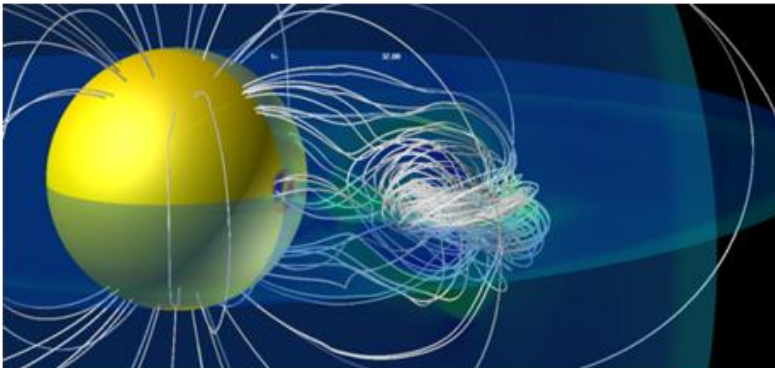
Total Magnetic Energy
Magnetic Free Energy
(J)



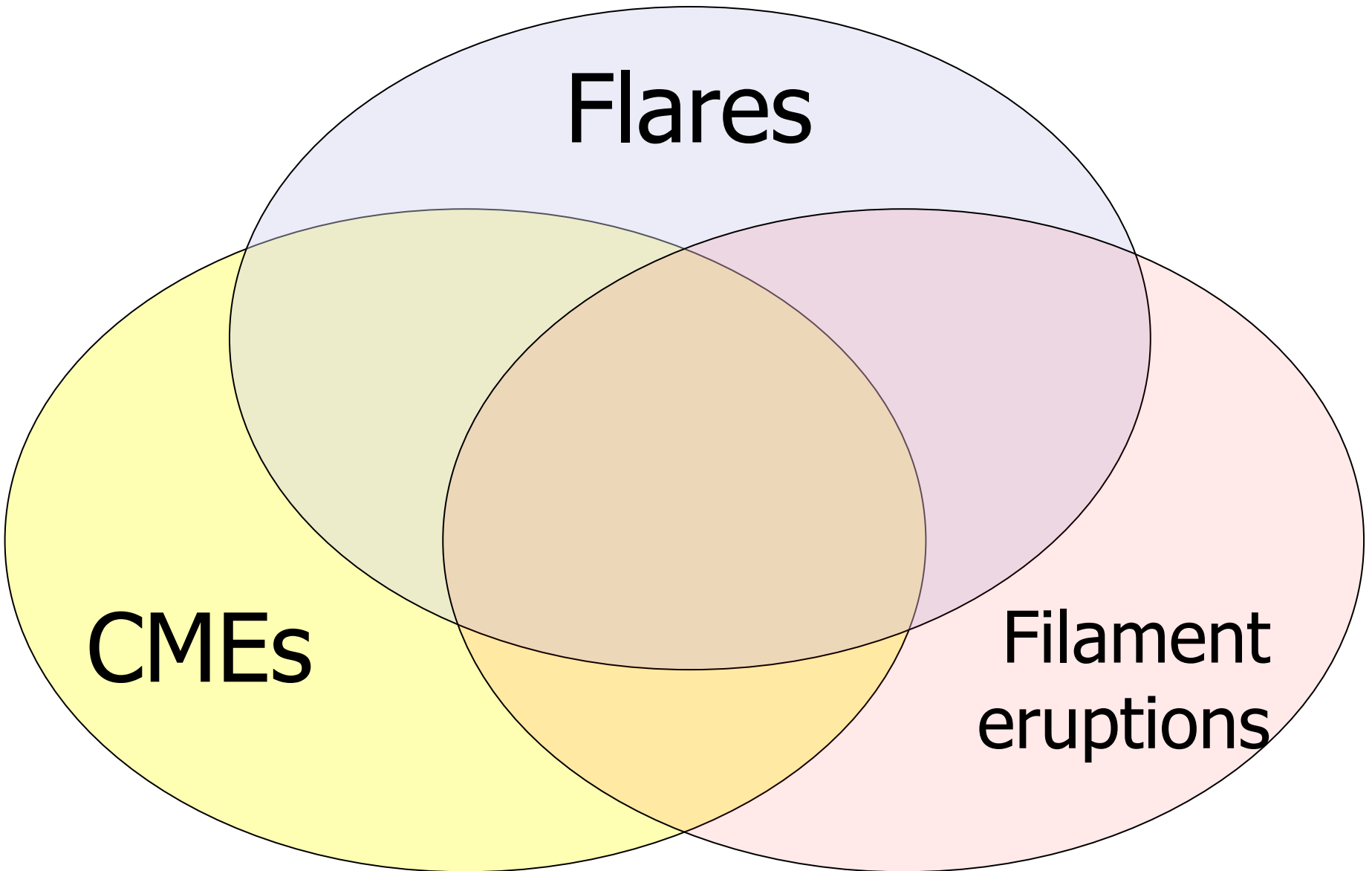
NLFF before & after flare



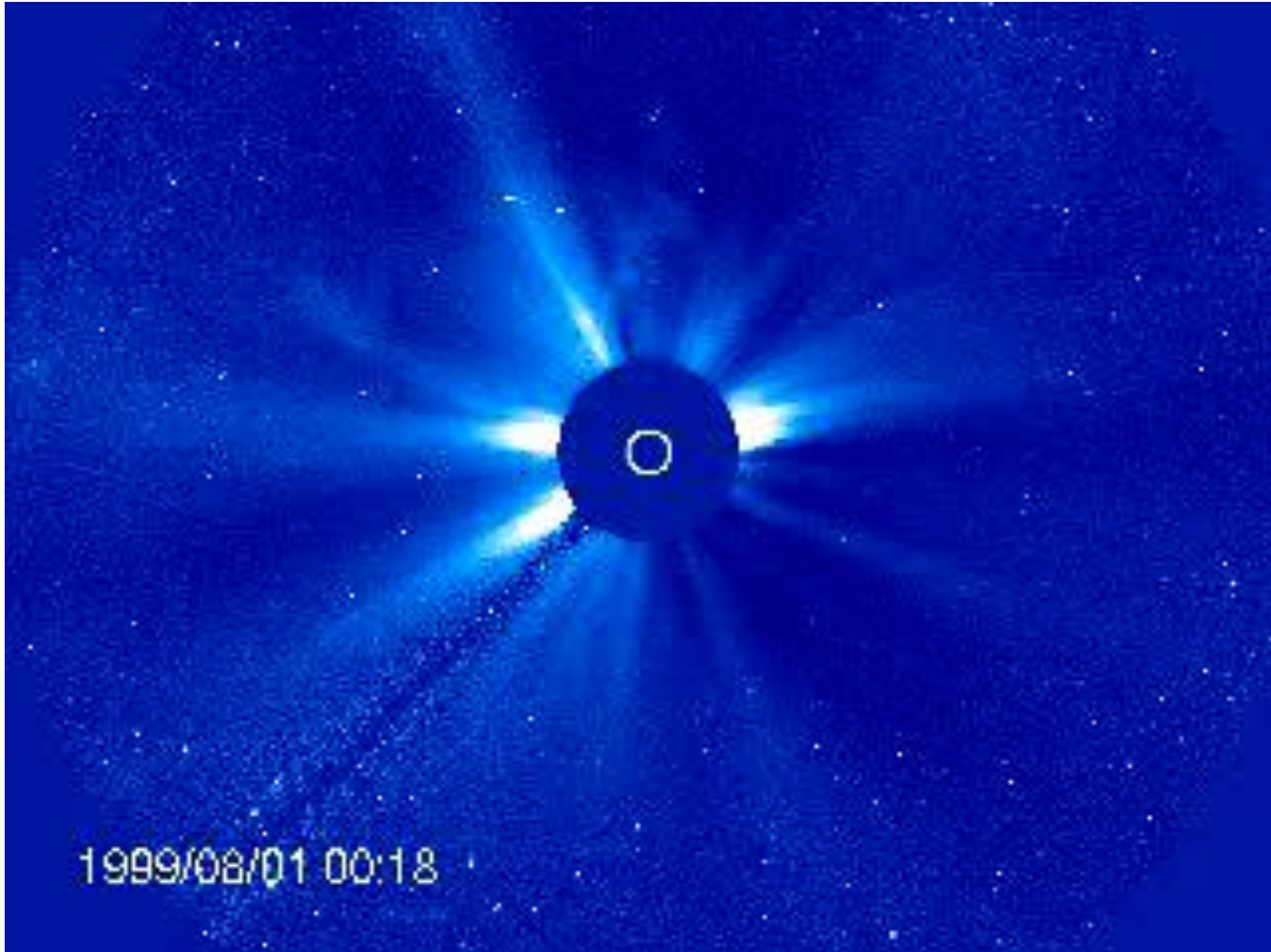
Dynamics in solar coronal magnetic field



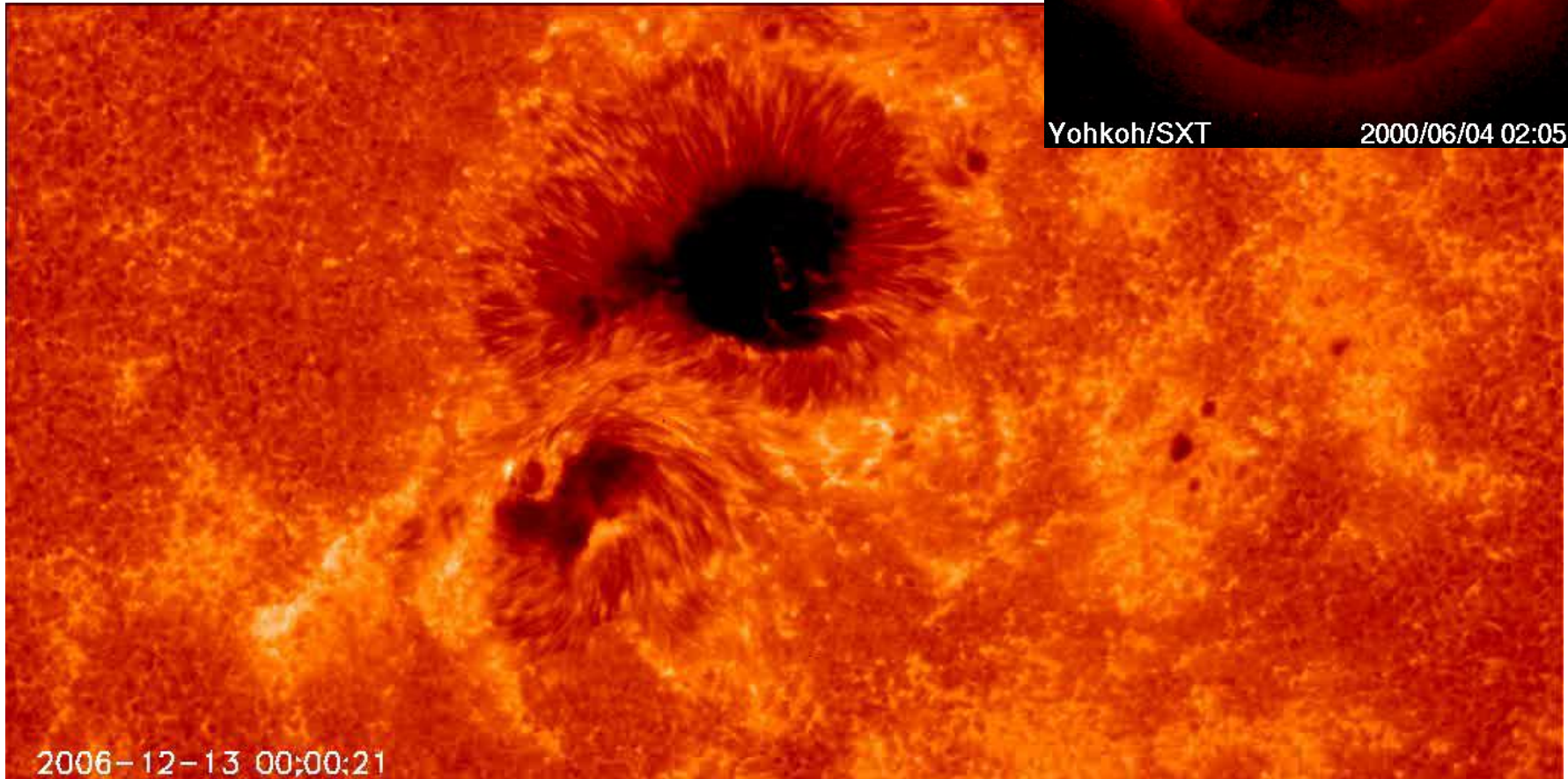
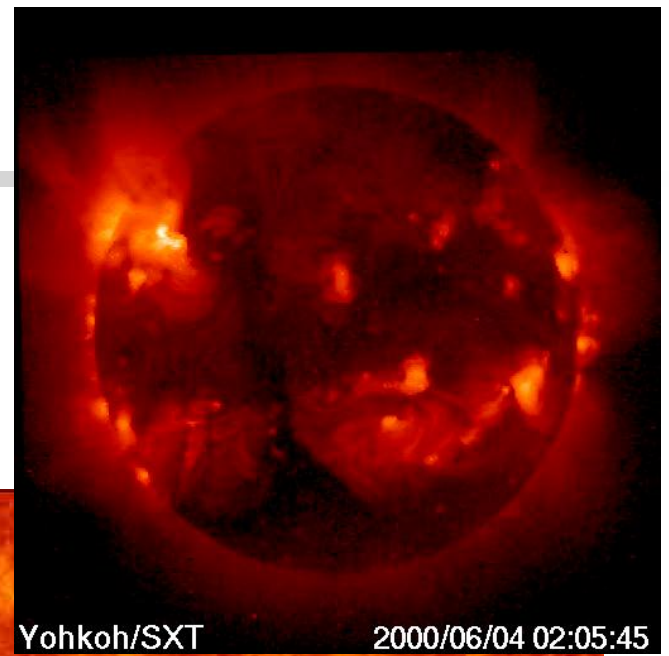
Solar Eruptions



CMEs



Solar Flares



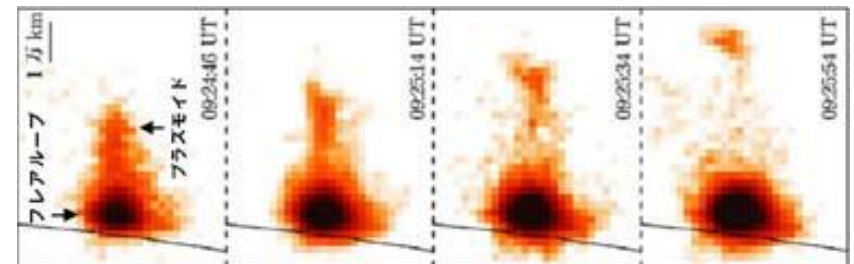
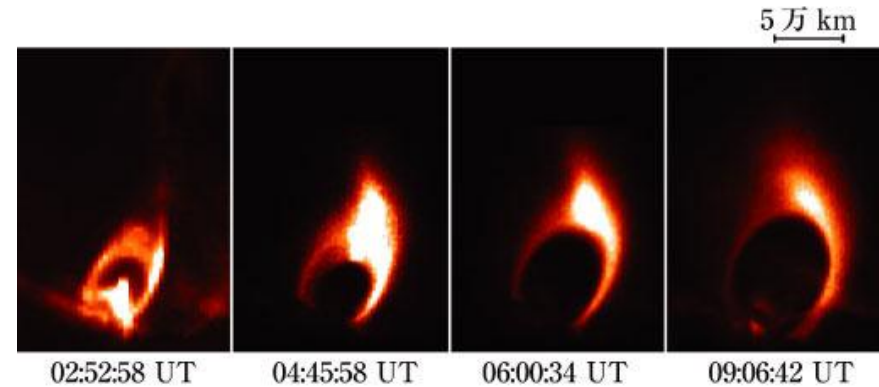
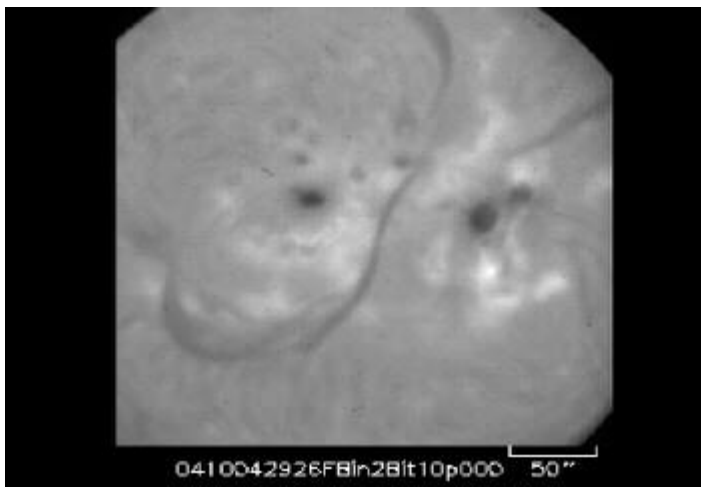
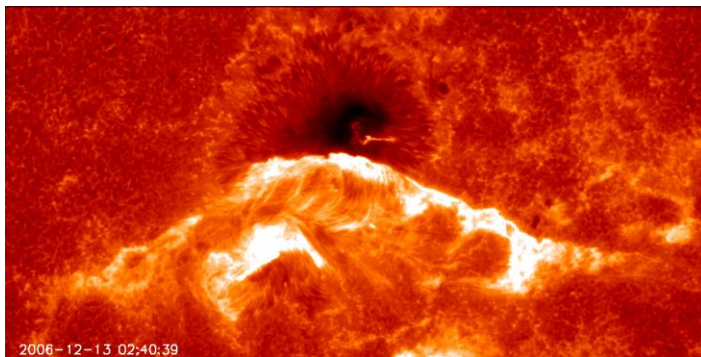
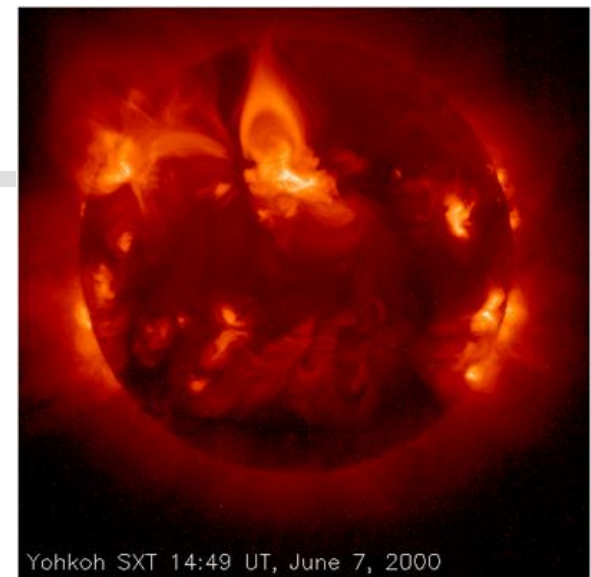
Properties of Flares

near sunspots

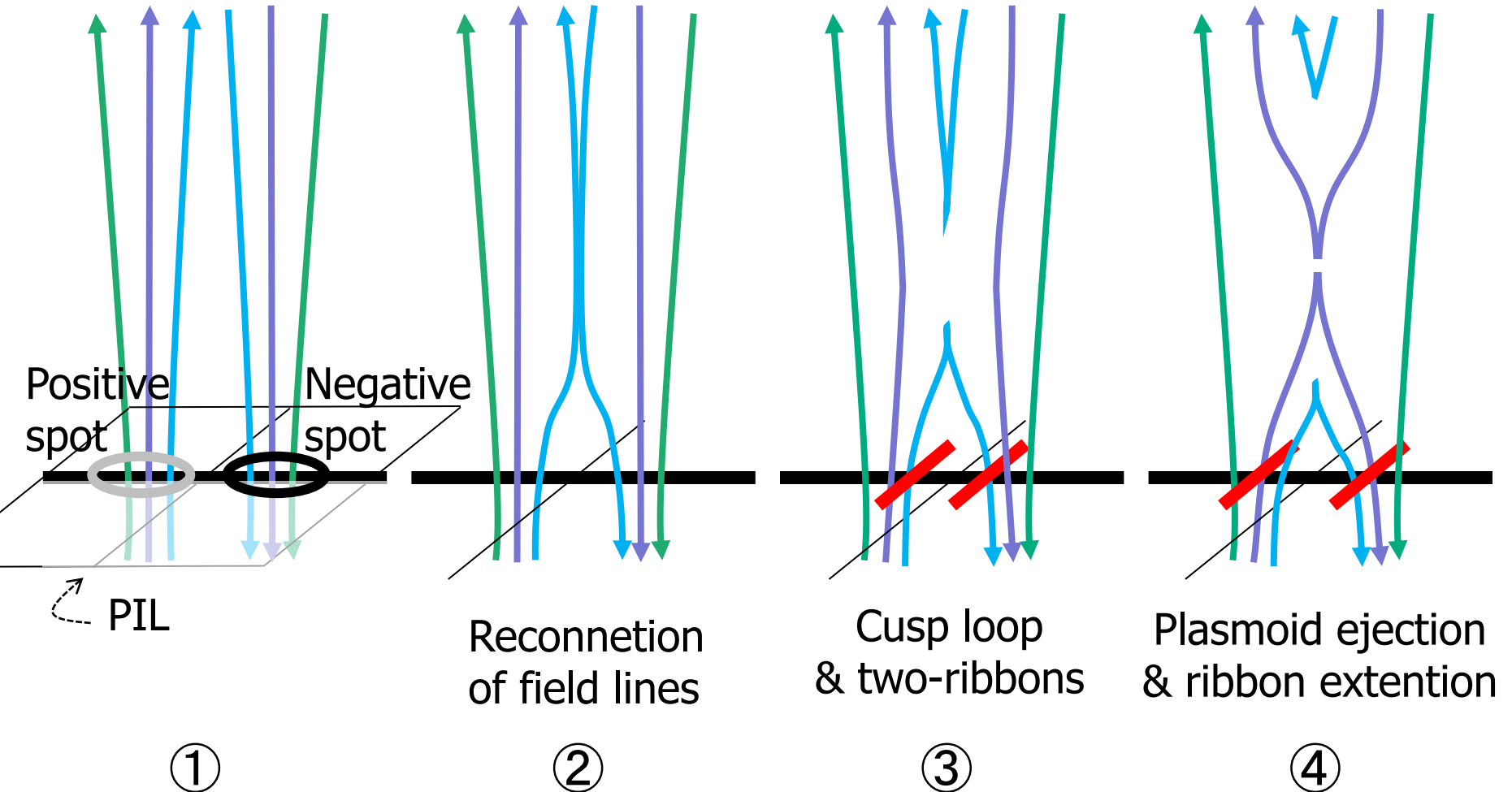
cusplike loop

two-ribbon

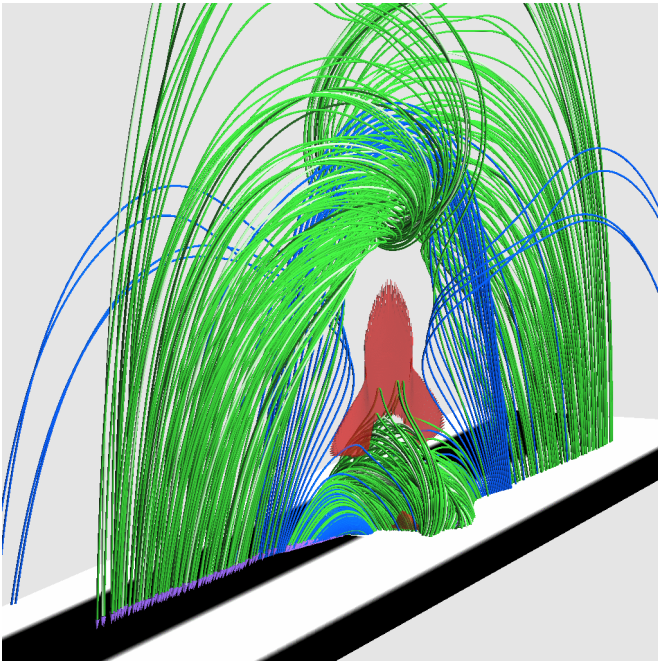
plasmoid ejection



Magnetic Reconnection Model



What triggers the onset of solar eruptions?



Prediction is important.

- For the space weather forecasting
 - When will giant flares and CMEs occur?
 - How is the geo-effectiveness?
- For the promotion of scientific understandings
 - New theories have been established through the efforts for prediction.
e.g. Halley's prediction (1682, 1758)



Papers for Flare Prediction

- Poisson statistics (Gallagher et al. 2002, Bloomfield1 et al 2012)
- Bayesian statistics (Wheatland 2005)
- wavelet predictors (Yu et al. 2010a)
- Bayesian networks (Yu et al. 2010b)
- vector machines (Li et al. 2007)
- discriminant analysis (Barnes et al. 2007)
- ordinal logistic regression (Song et al. 2009; Yuan et al. 2010)
- neural networks (Colak & Qahwaji 2009; Yu et al. 2009; Ahmed et al. 2012)
- predictor teams (Huang et al. 2010)
- superposed epoch analysis (Mason & Hoeksema 2010)
- empirical projections (Falconer et al. 2011).

Skill Score of X-flare prediction

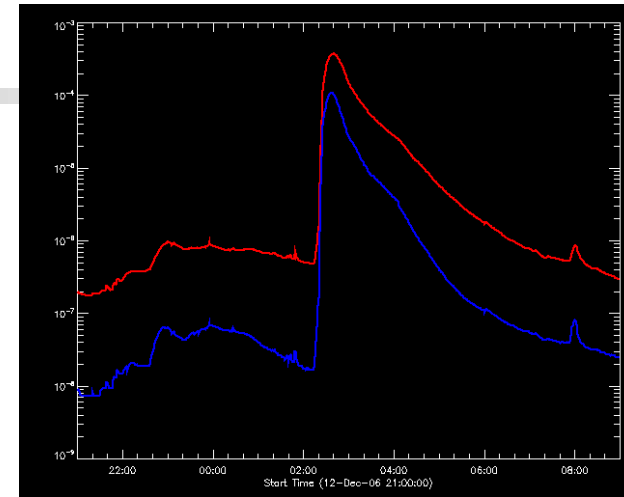
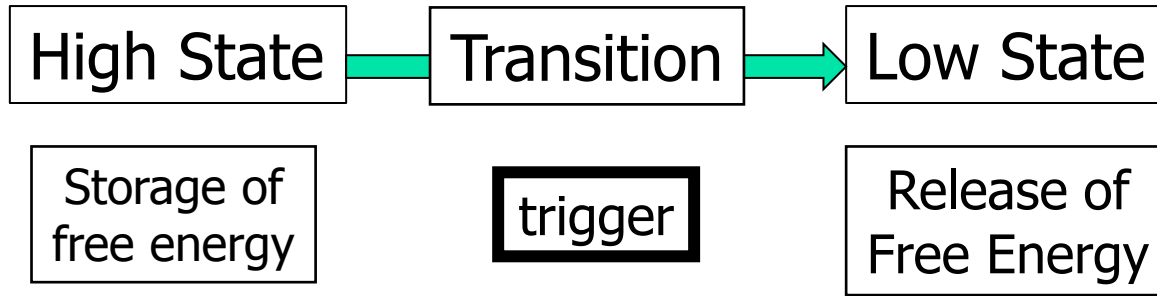
1day	2day	3day	year (events)
-0.068	-0.096	-0.141	2011 (8)
0.112	-0.147	-0.171	2006 (4)
0.242	0.147	0.127	2005 (13)
0.052	-0.001	-0.044	2004 (9)
0.200	0.093	0.076	2003 (17)
-0.037	-0.050	-0.033	2002 (12)
-0.061	-0.034	-0.006	2001 (18)



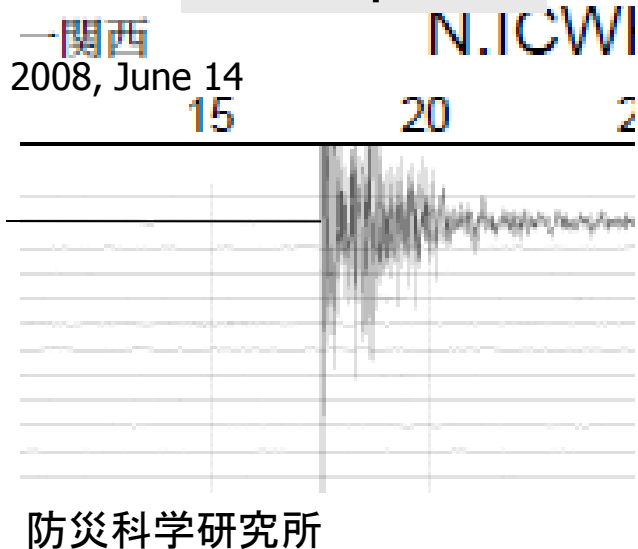
http://www.swpc.noaa.gov/forecast_verification/

$$SS = \frac{n_{ff} - (n_q - n_{qq})}{n_f}$$

Storage & Release Process

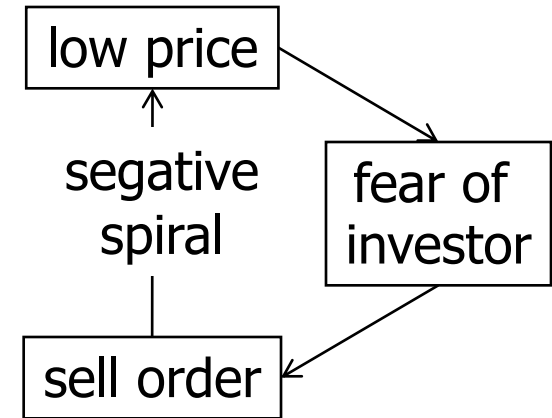
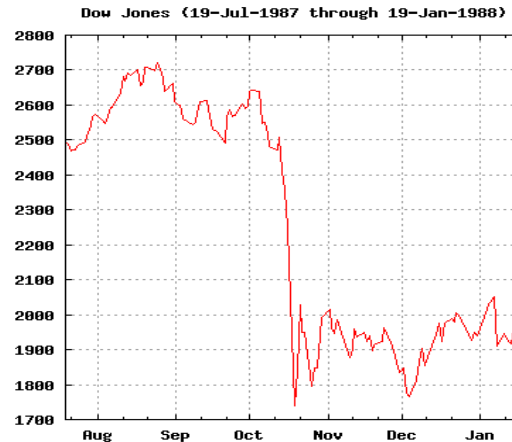


earthquake



stock market

(Dow Jones in Black Monday)



Empirical Prediction

Analog Method

Problem

What are the best key parameters to discriminate flare productive active regions?

prediction
(future)

probability

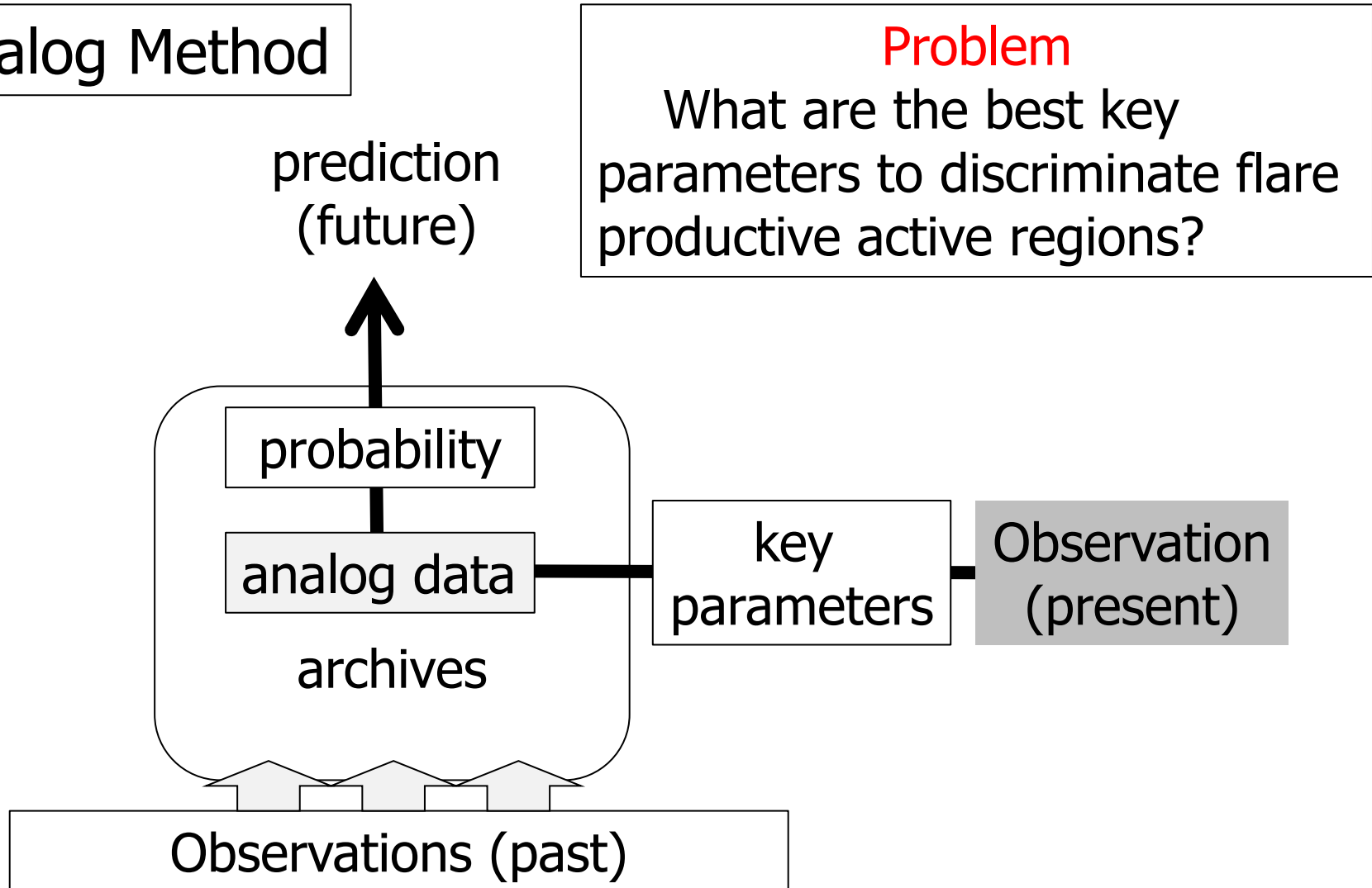
analog data

archives

key
parameters

Observation
(present)

Observations (past)



McIntosh classification

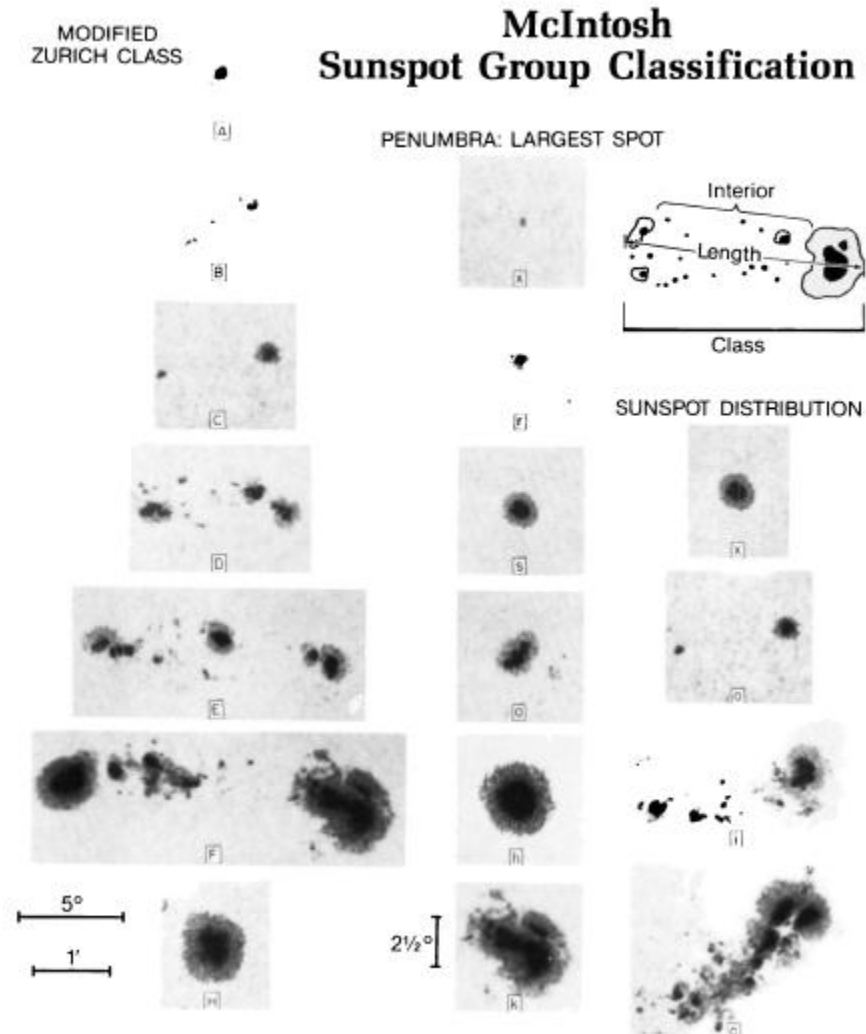


Fig. 1. The 3-component McIntosh classification, with examples of each category.

Flare Prob. for each McIntosh class

- Gallacher, Moon, Wang 2002 Sol. Phys.

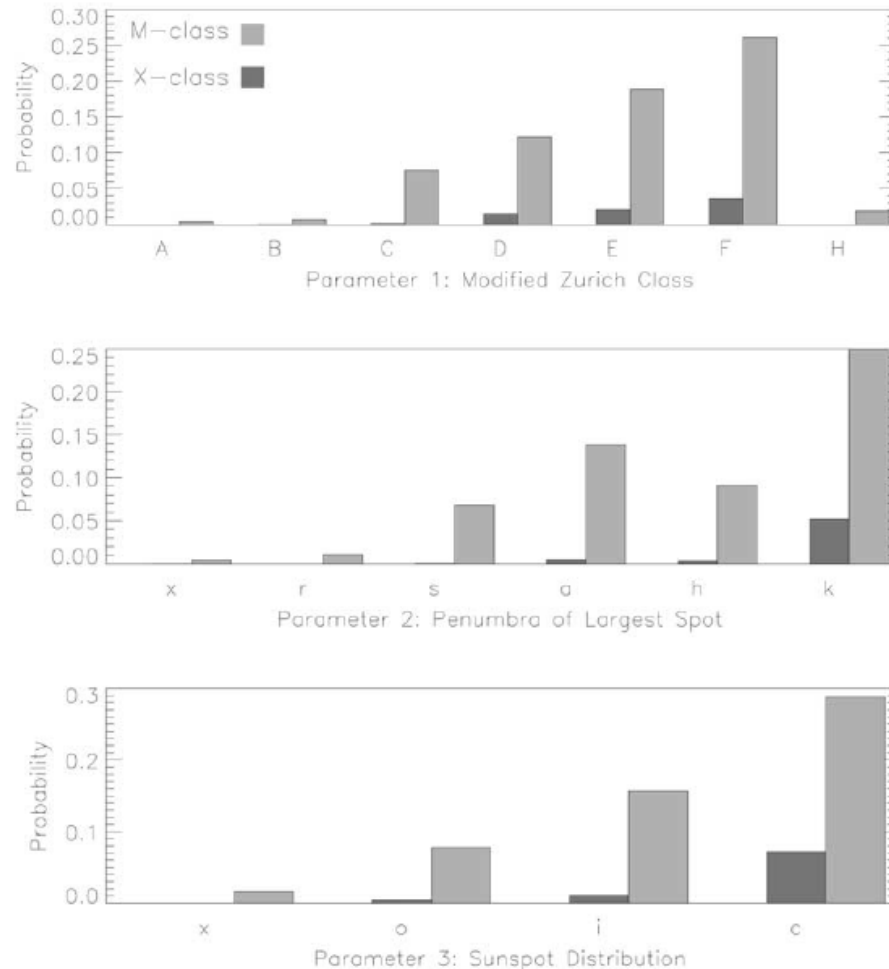
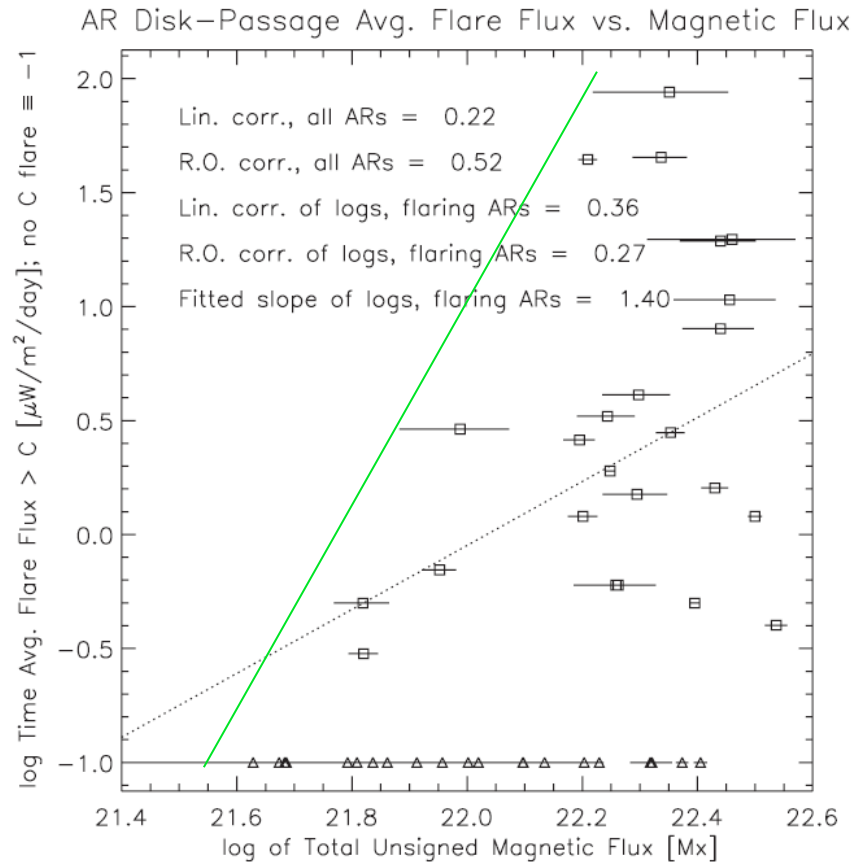


Figure 4. Derived 24-hour active-region flare probabilities for each of the three McIntosh classification parameters using Poisson statistics.

Welsch et al. 2009 ApJ

- The total magnetic flux decides the maximum flare size.

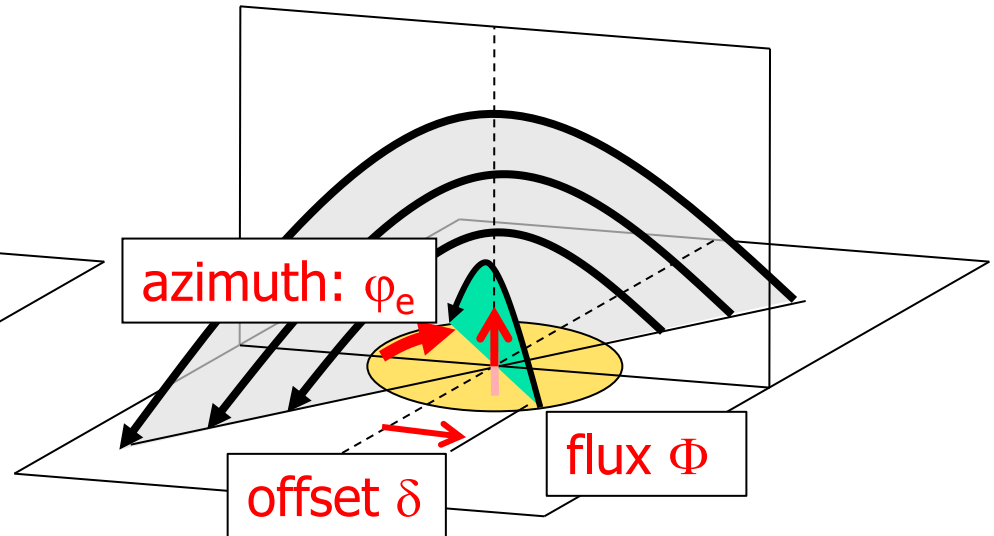
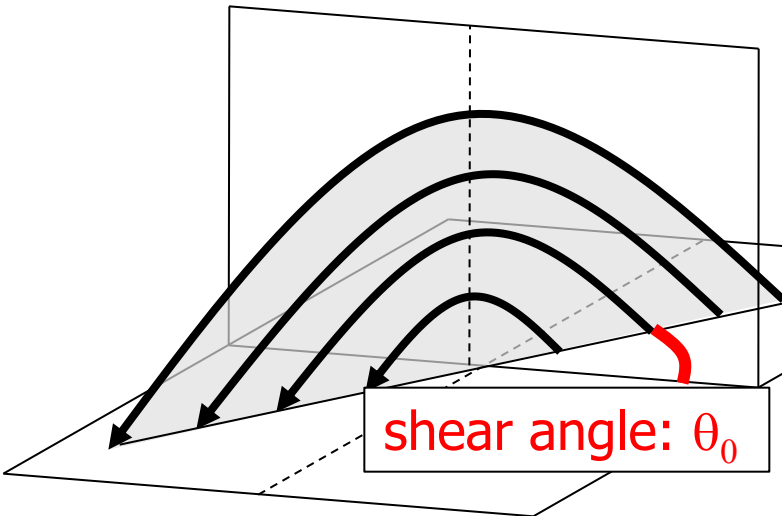


Ensemble Simulation Study

Large field
(free energy)

&

Small field
(trigger)



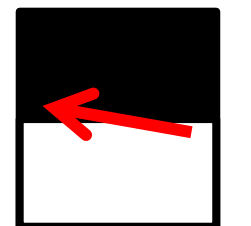
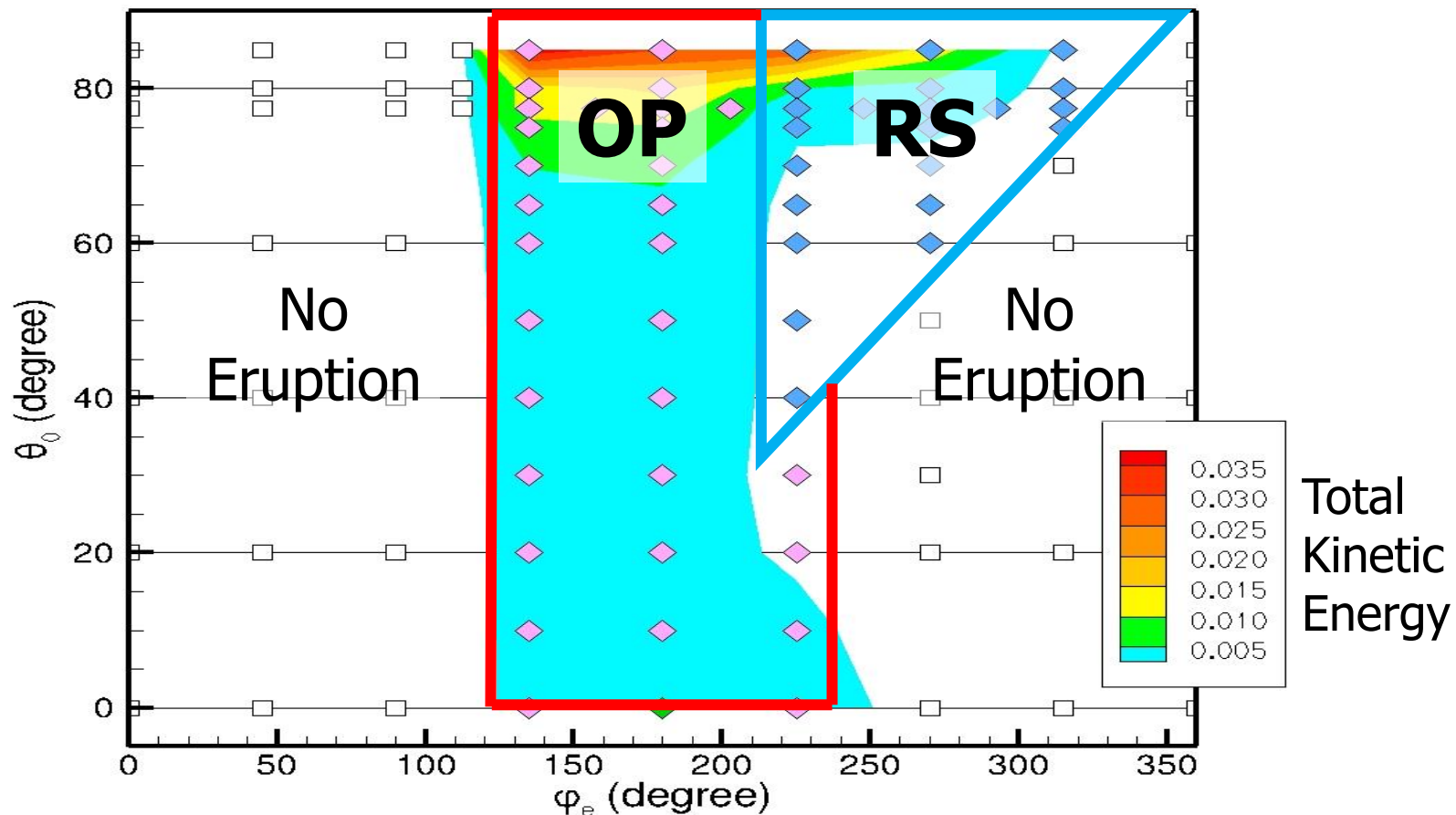
Box: Rectangle including PIL
Initial condition: LFFF

BC: imposing the electric field to
simulate flux emerging

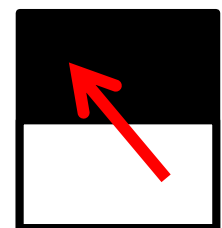
161
simulations

- 3D MHD (zero-beta model)
- 256x1024x512 grids (finite difference scheme)
- output: 800 GB/run

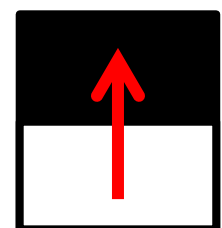
Simulation Results



strong shear

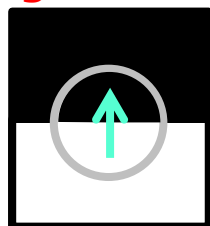


weak shear



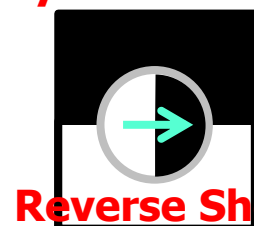
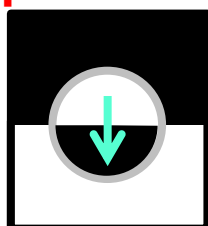
potential field

Right Polarity



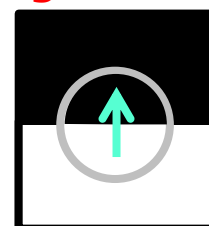
Normal Shear

Opposite Polarity



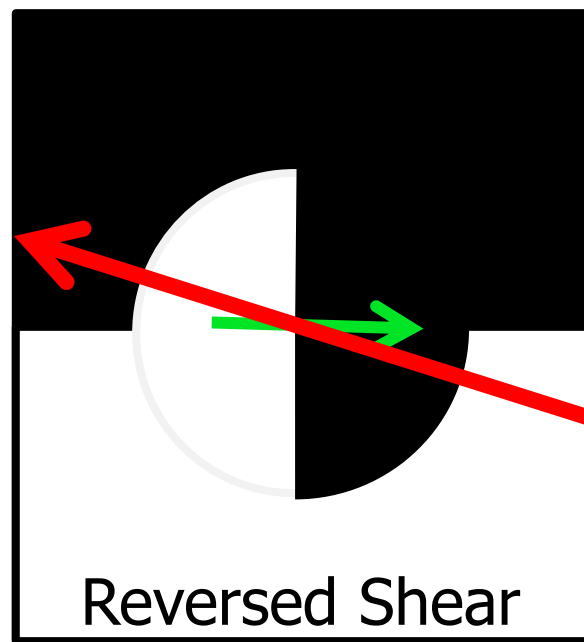
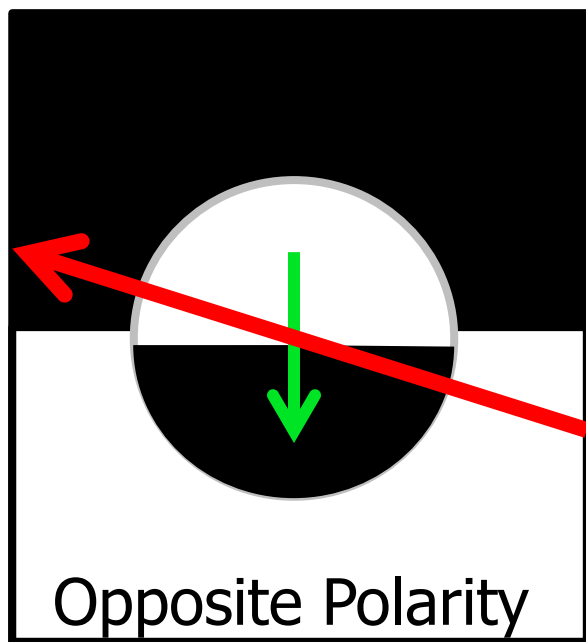
Reverse Shear

Right Polarity

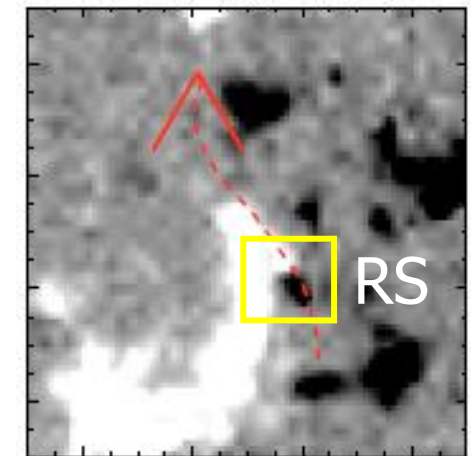
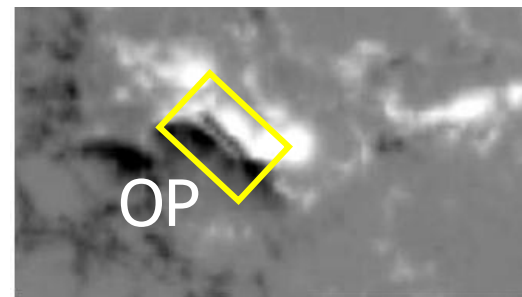
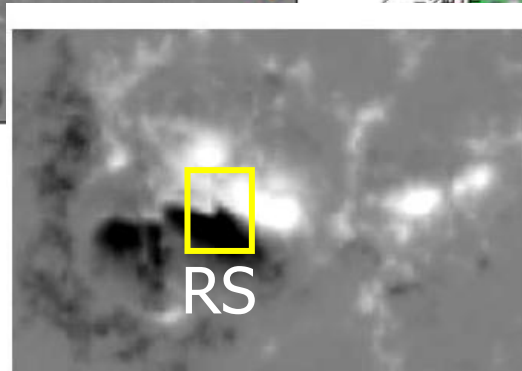
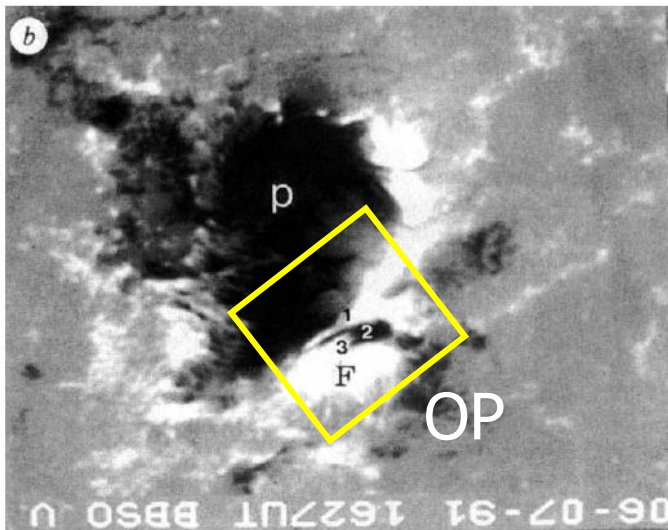
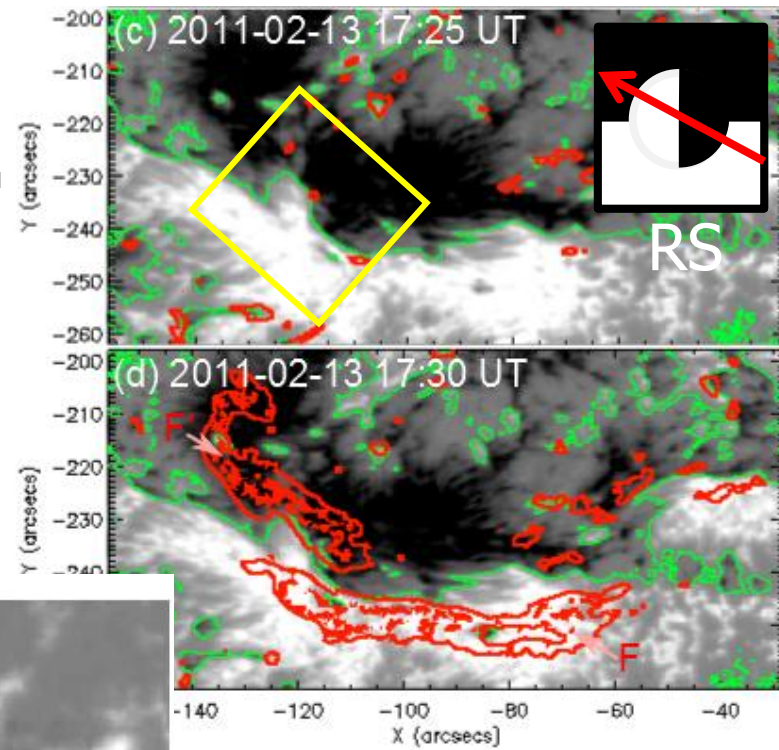
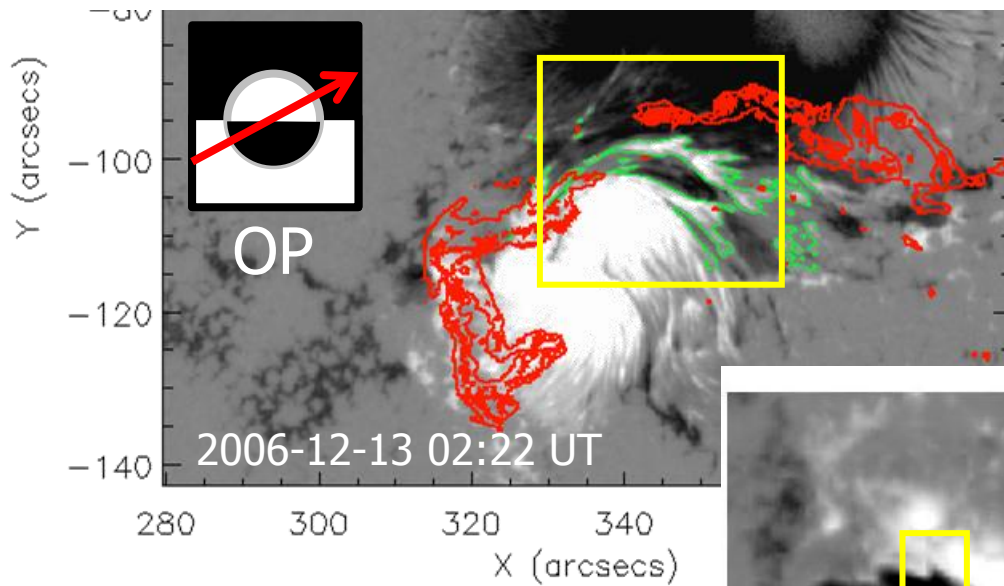


Two Structures Triggering Eruption

- There are the two different structures (OP and RS) favorable to the onset of solar flares.



Observations



Zirin and Wang 1993

Kurokawa, Wang & Ishii 2002

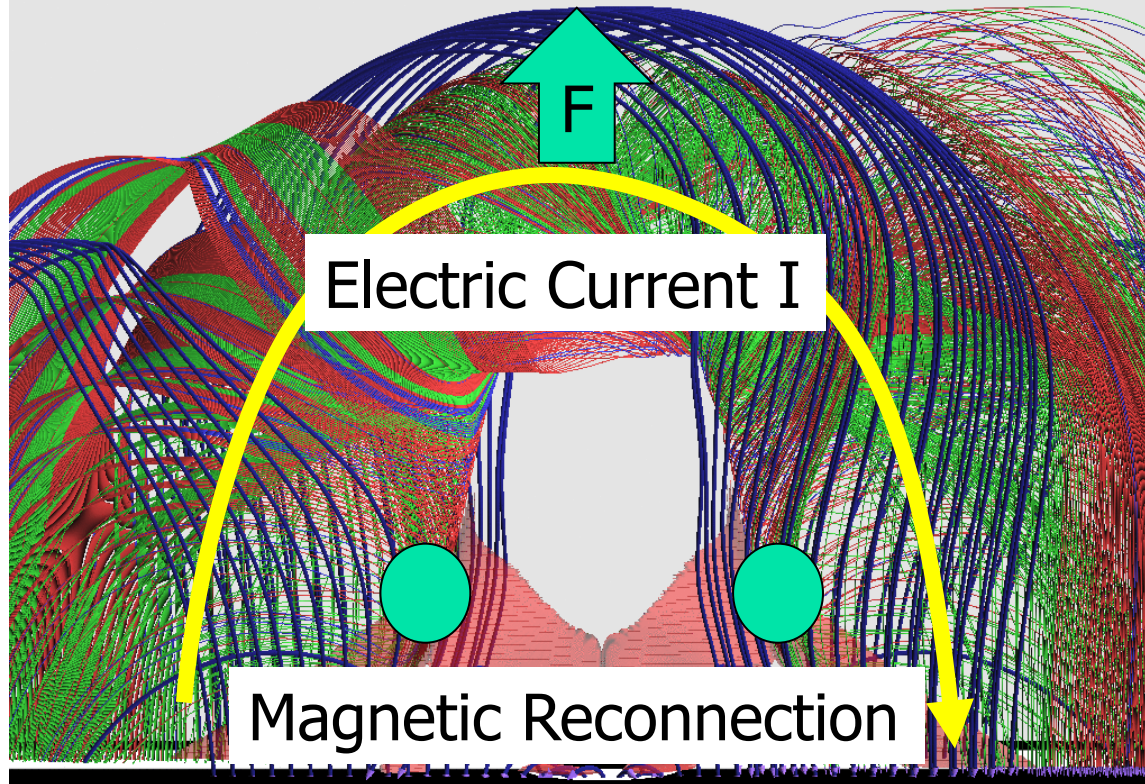
Green, Kliem & Wallace 2011

Eruption & Reconnection (OP)

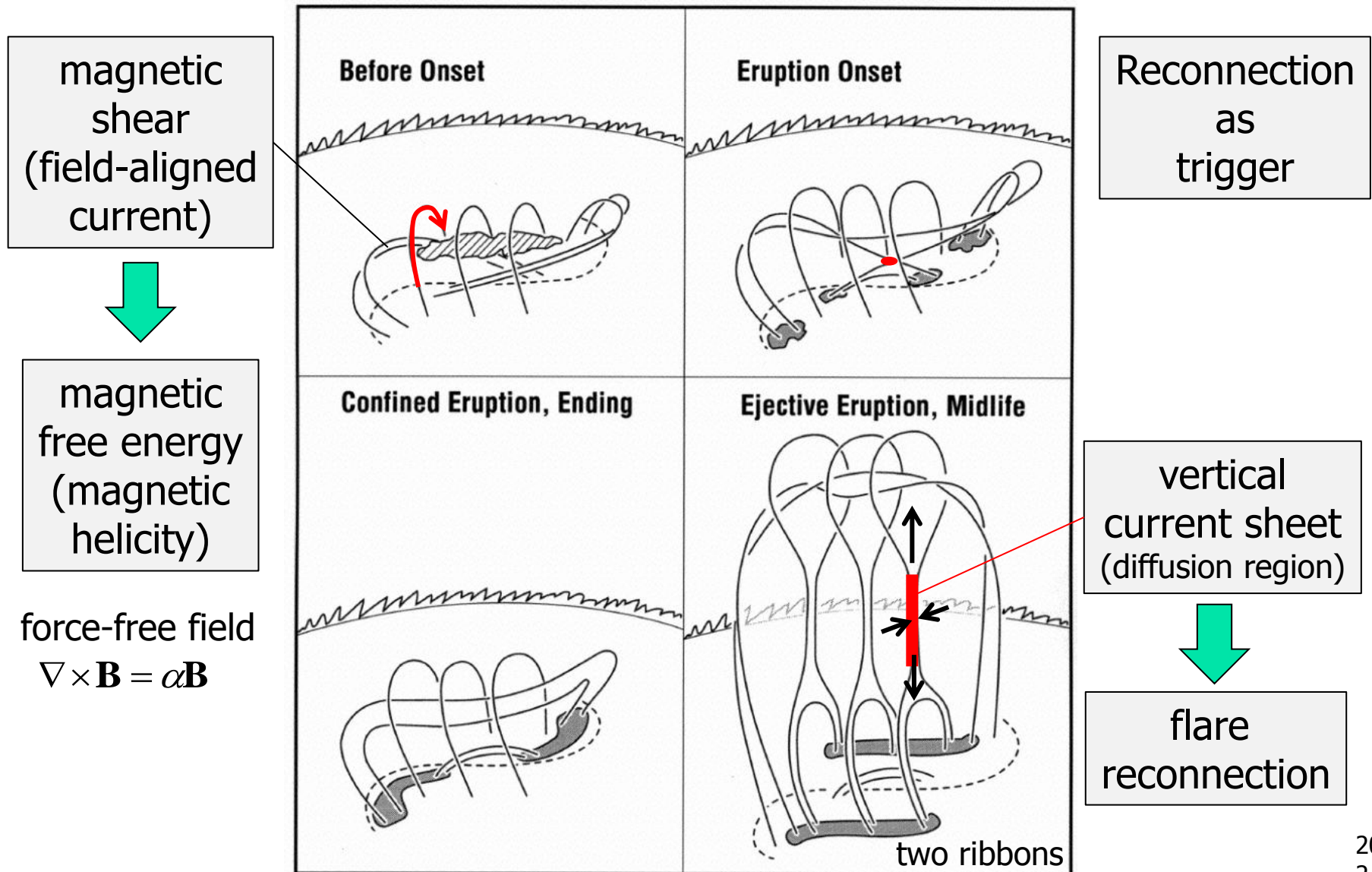
Tether cutting model
Moore & Roumeliotis
1992

$$F = r_c I^2 - B_p I$$

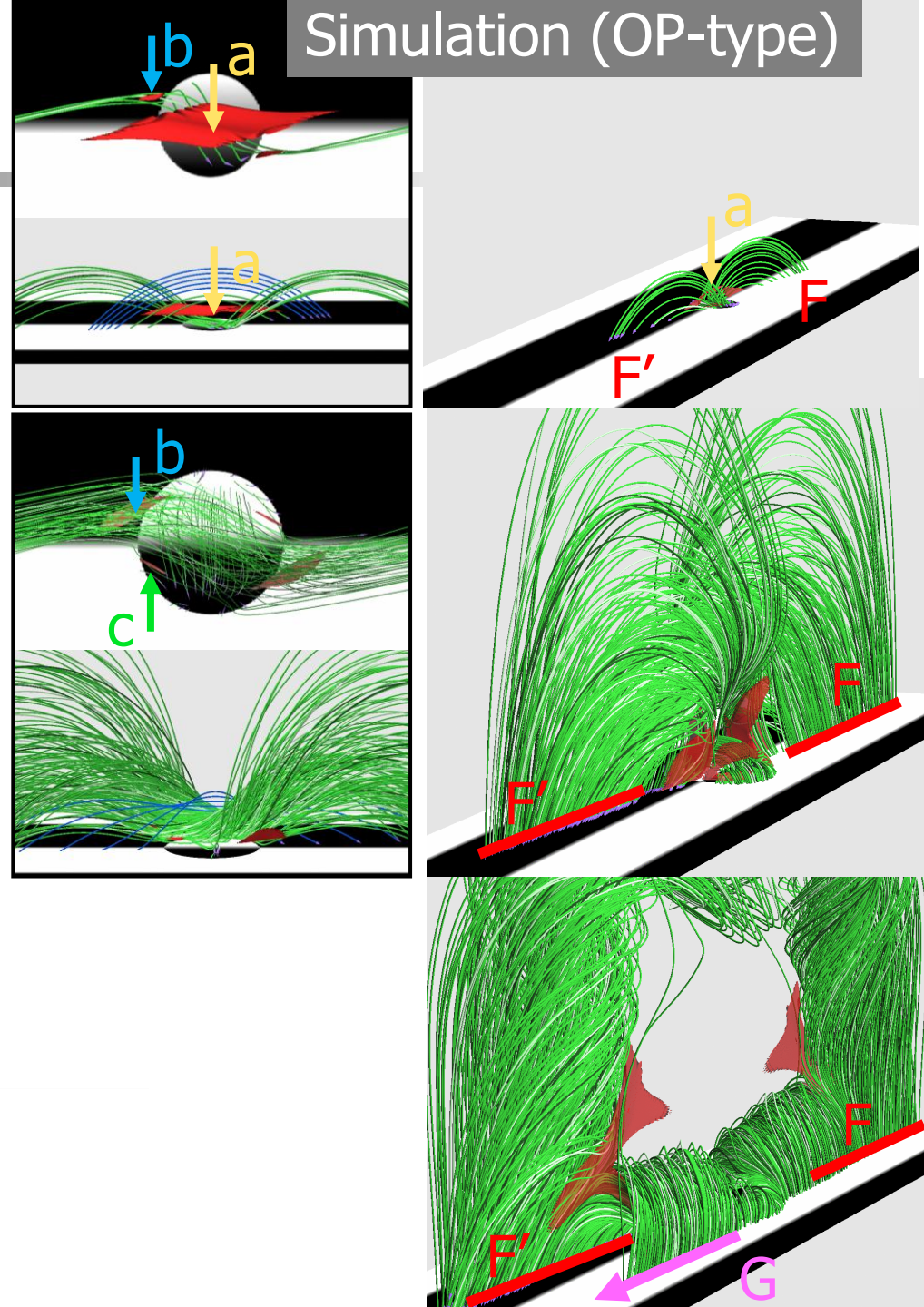
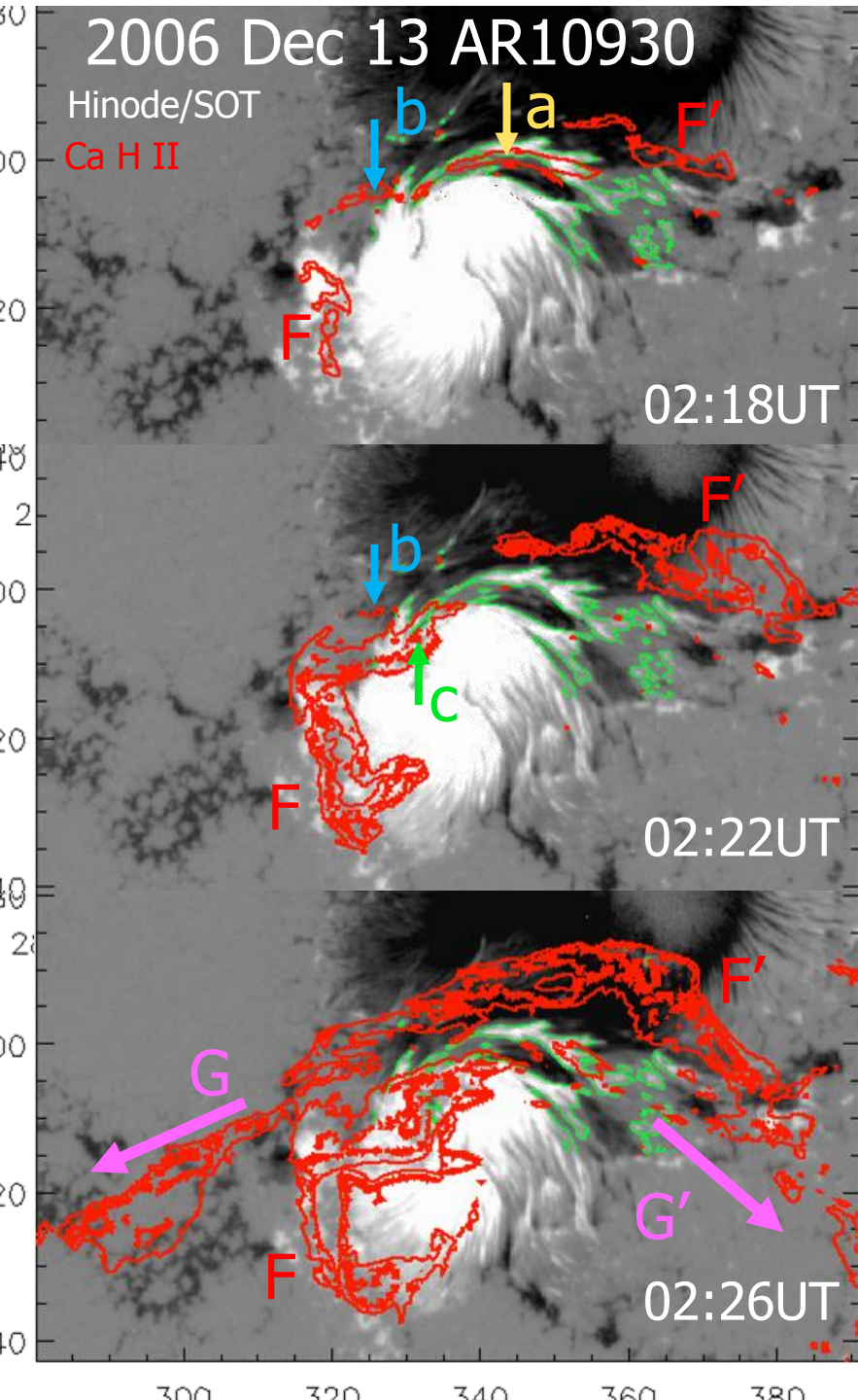
Loss of equilibrium
Forbes & Priest 1995
Torus Instability
Kliem & Torok 2006



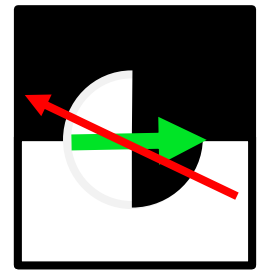
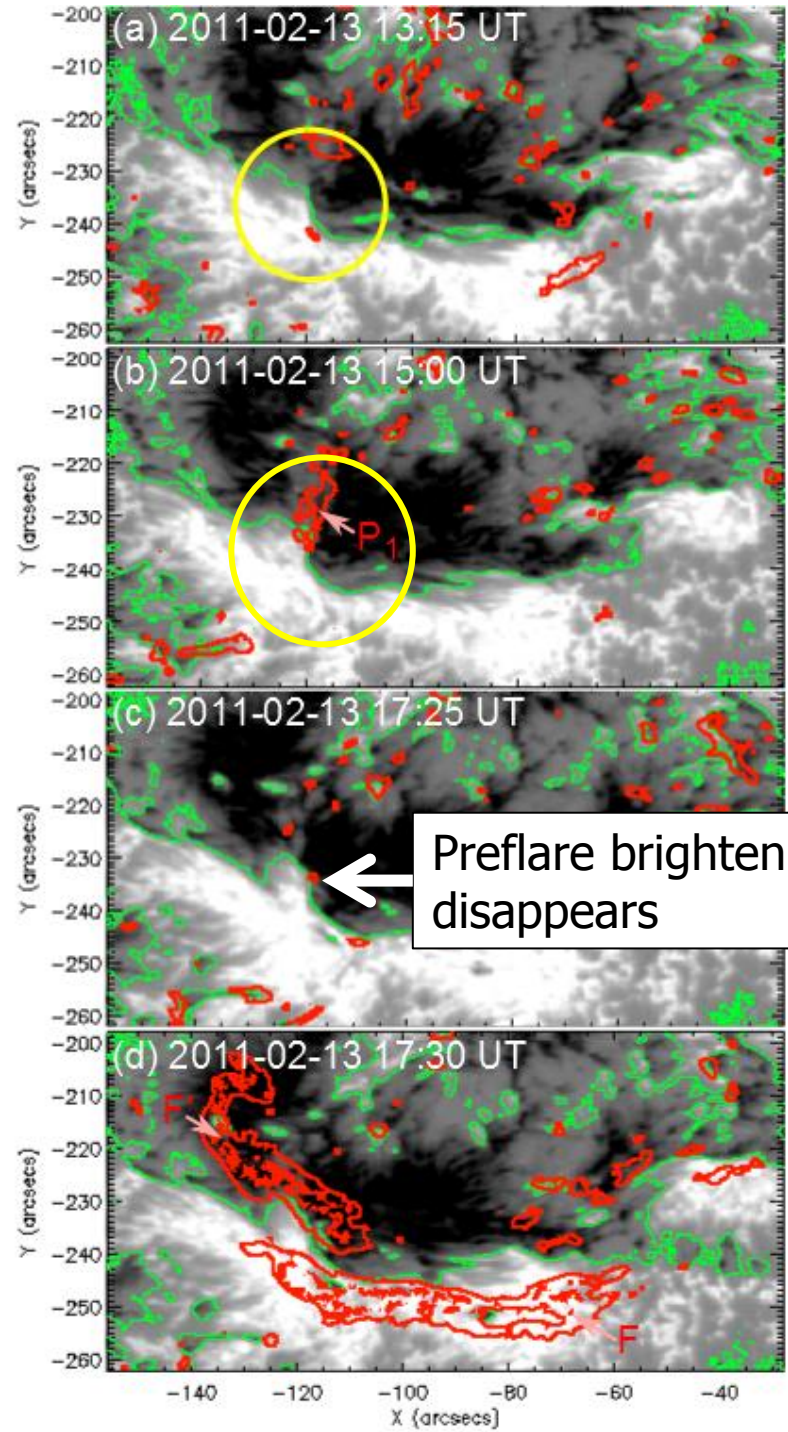
Tether Cutting Scenario



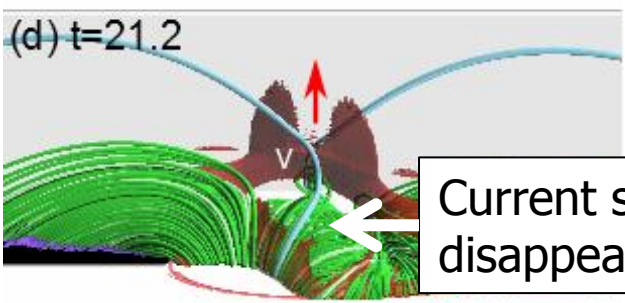
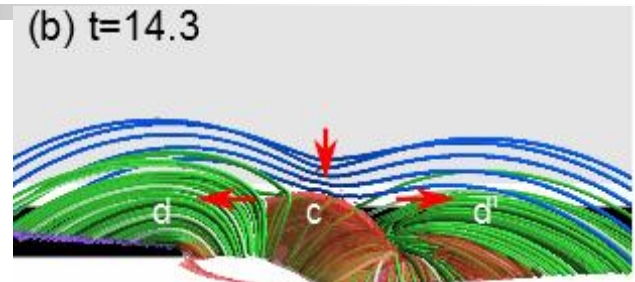
Moor et al. 2001



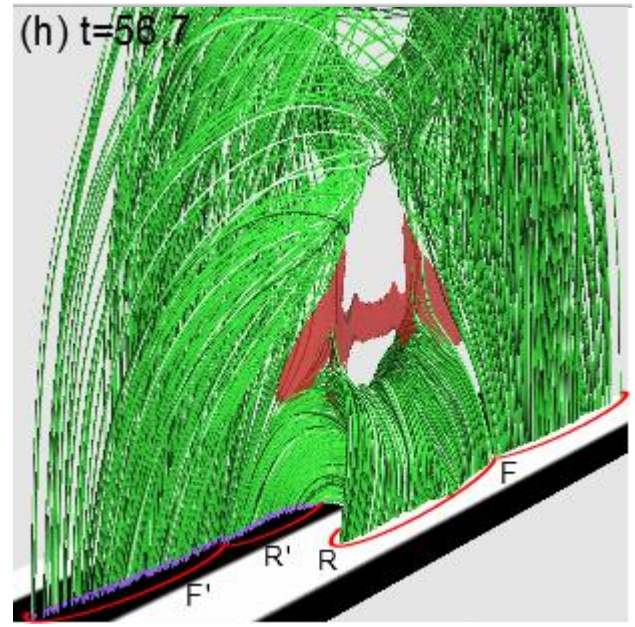
Simulation (RS-type)



RS configuration



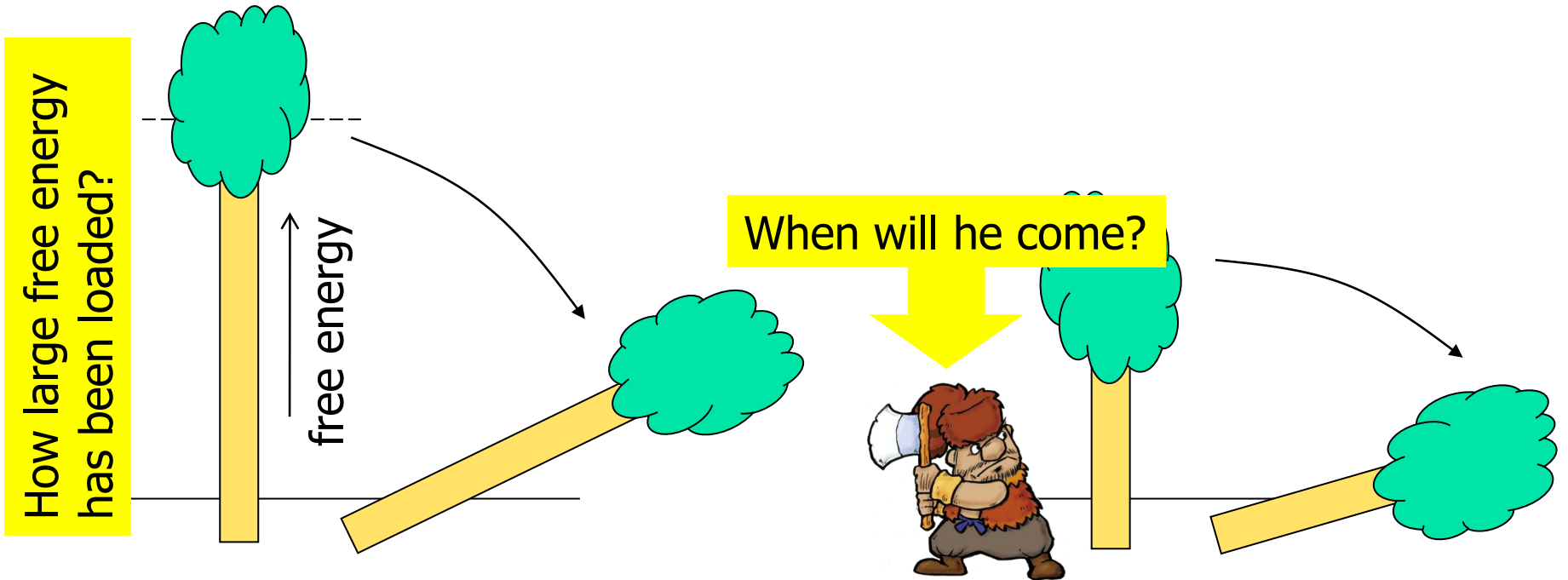
Current sheet disappears



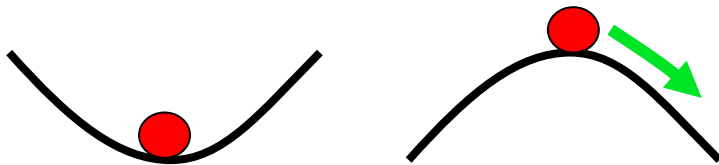
The Onset of Storage-and-Release

Critical Phenomena

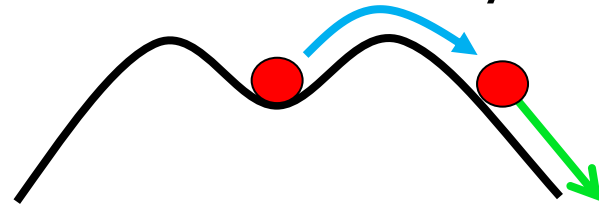
Triggered Phenomena



Linear instability



Nonlinear instability



Summary

- We find that the two different structures (OP and RS) favorable to the onset of solar flares in terms of the ensemble simulations for different magnetic configurations.
- The detail comparison with Hinode and other observations demonstrates that events indeed occurred, which are well consistent with the two scenarios.
- It means that the solar forecast is possible in terms of the sophisticate magnetic observation. However, the lead time of deterministic forecast of flares must be limited by the time-scale of small magnetic structures and flow driver, which is about several hours, presumably.
- The longer term forecast could be performed in a probabilistic manner.